## High Speed, Logic Isolator with Power Transformer

## FEATURES

IsoLogic ${ }^{\text {TM }}$ Circuit Architecture
Isolation Test Voltage: To 3.5 kV rms
Five Isolated Logic Lines: Available in Six I/O Configurations
Logic Signal Bandwidth: 20 MHz (Min), 40 mbps (NRZ)
Isolated Power Transformer: 37 V p-p, 1.5 W Max
CMV Transient Immunity: 10 kV/ $\mu \mathrm{s}$ Min
Waveform Edge Transmission Symmetry: $\pm 1$ ns
Field and System Output Enable/Three-State Functions
Performance Rated Over $-25^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$
UL1950, IEC950, EN60950 Certification, Pending

## APPLICATIONS

PLC/DCS Analog Input and Output Cards
Communications Bus Isolation
General Data Acquisition Applications
IGBT Motor Drive Controls
High Speed Digital I/O Ports

## GENERAL DESCRIPTION

The AD260 is designed using Analog Devices new IsoLogic circuit architecture to isolate five digital control signals to/ from a microcontroller and its related field I/O components. Six models allow all I/O combinations from five input lines to five output lines, including combinations in between. Every AD260 effectively replaces up to five opto-isolators while also providing the 1.5 W transformer for a 3.5 kV isolated dc-dc power supply circuit.
Each line of the AD260 has a bandwidth of $20 \mathrm{MHz}(\mathrm{min})$ with a propagation delay of only 14 ns , which allows for extremely fast data transmission. Output waveform symmetry is maintained to within $\pm 1 \mathrm{~ns}$ of the input so the AD260 can be used to accurately isolate time-based PWM signals.
All field or system output pins of the AD260 can be set to a high resistance three-state level by use of the two enable pins. A field output three-stated offers a convenient method of presetting logic levels at power-up by use of pull-up/down resistors. System side outputs being three-stated allows for easy multiplexing of multiple AD260s.

The isolation barrier of the AD260 B Grade is $100 \%$ tested at 3.5 kV rms (system to field). The barrier design also provides excellent common-mode transient immunity from $10 \mathrm{kV} / \mu \mathrm{s}$ common-mode voltage excursions of field side terminals relative to the system side, with no false output triggering on either side.
Each output is updated within nanoseconds by input logic transitions, the AD260 also has a continuous output update feature that automatically updates each output based on the dc level of

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## REV. 0

## FUNCTIONAL BLOCK DIAGRAM


the input. This guarantees the output is always valid $10 \mu \mathrm{~s}$ after a fault condition or after the power-up reset interval.
The AD260 also has an integral center tap transformer for generating isolated power. Typically driven by a 5 V push-pull drive at the primary, it will generate a 37 V p-p output capable of supplying up to 1.5 W . This can then be regulated to the desired voltage, including $\pm 5 \mathrm{~V}$ dc for circuit components and 24 V for a 20 mA loop supply when needed.

## PRODUCT HIGHLIGHTS

Six Isolated Logic Line I/O Configurations Available: The AD260 is available in six pin-compatible versions of I/O configurations to meet a wide variety of requirements.
Wide Bandwidth with Minimal Edge Error: The AD260 with IsoLogic affords extremely fast isolation of logic signals due to its 20 MHz bandwidth and 14 ns propagation delay. It maintains a waveform input-to-output edge transition error of typically less than $\pm 1 \mathrm{~ns}$ (total) for positive vs. negative transition.
$3.5 \mathbf{k V}$ rms Test Voltage Isolation Rating: The AD260 B Grade is rated to operate at 1.25 kV rms and is $100 \%$ production tested at 3.5 kV rms , using a standard ADI test method.
High Transient Immunity: The AD260 rejects commonmode transients slewing at up to $10 \mathrm{kV} / \mu \mathrm{s}$ without false triggering or damage to the device.
(Continued on page 6)

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| Parameter | Conditions | Min | Typ | Max | Units |
| :---: | :---: | :---: | :---: | :---: | :---: |
| INPUT CHARACTERISTICS <br> Threshold Voltage <br> Positive Transition $\left(\mathrm{V}_{\mathrm{T}+}\right)$ <br> Negative Transition ( $\mathrm{V}_{\mathrm{T}}$ ) <br> Hysteresis Voltage ( $\mathrm{V}_{\mathrm{H}}$ ) <br> Input Capacitance ( $\mathrm{C}_{\mathrm{IN}}$ ) <br> Input Bias Current ( $\mathrm{I}_{\mathrm{IN}}$ ) | Per Input | $\begin{aligned} & 2.0 \\ & 3.0 \\ & 0.9 \\ & 1.2 \\ & 0.4 \\ & 0.5 \end{aligned}$ | $\begin{aligned} & 2.7 \\ & 3.2 \\ & 1.8 \\ & 2.2 \\ & 0.9 \\ & 1.0 \\ & 5 \\ & 0.5 \end{aligned}$ | $\begin{aligned} & 3.15 \\ & 4.2 \\ & 2.2 \\ & 3.0 \\ & 1.4 \\ & 1.5 \end{aligned}$ | $\begin{aligned} & \mathrm{V} \\ & \mathrm{~V} \\ & \mathrm{~V} \\ & \mathrm{~V} \\ & \mathrm{~V} \\ & \mathrm{~V} \\ & \mathrm{pF} \\ & \mu \mathrm{~A} \end{aligned}$ |
| OUTPUT CHARACTERISTICS <br> Output Voltage ${ }^{1}$ <br> High Level ( $\mathrm{V}_{\mathrm{OH}}$ ) <br> Low Level ( $\mathrm{V}_{\text {OL }}$ ) <br> Output Three-State Leakage Current | $\begin{aligned} & +5 \mathrm{Vdc} c_{\text {YYS }}=4.5 \mathrm{~V},\left\|\mathrm{I}_{\mathrm{O}}\right\|=0.02 \mathrm{~mA} \\ & +5 \mathrm{Vdc} \mathrm{Ic}_{\text {YS }}=4.5 \mathrm{~V},\left\|\mathrm{I}_{\mathrm{O}}\right\|=4 \mathrm{~mA} \\ & +5 \mathrm{Vdc} c_{\text {YS }}=4.5 \mathrm{~V},\left\|\mathrm{I}_{\mathrm{O}}\right\|=0.02 \mathrm{~mA} \\ & +5 \mathrm{Vdc} c_{\text {YS }}=4.5 \mathrm{~V},\left\|\mathrm{I}_{\mathrm{O}}\right\|=4 \mathrm{~mA} \end{aligned}$ <br> ENABLE $_{\text {SYSFLD }}$ @ Logic Low/High Level Respectively | $\begin{aligned} & 4.4 \\ & 3.7 \end{aligned}$ | 0.5 | $\begin{aligned} & 0.1 \\ & 0.4 \end{aligned}$ | $\begin{aligned} & \mathrm{V} \\ & \mathrm{~V} \\ & \mathrm{~V} \\ & \mathrm{~V} \\ & \mu \mathrm{~A} \end{aligned}$ |
| DYNAMIC RESPONSE ${ }^{1}$ (Refer to Figure 2) <br> Max Logic Signal Frequency (f fin ) Waveform Edge Symmetry Error (terror $)$ Logic Edge Propagation Delay ( $\mathrm{t}_{\text {PHL }}, \mathrm{t}_{\text {PLH }}$ ) Minimum Pulsewidth ( $\mathrm{t}_{\text {PWMIN }}$ ) Max Output Update Delay on Fault or After Power-Up Reset Interval ( $\sim 30 \mu \mathrm{~s})^{2}$ | $\begin{aligned} & 50 \% \text { Duty Cycle, }+5 \mathrm{~V} \mathrm{dc} \mathrm{sys}=5 \mathrm{~V} \\ & \text { tphL }^{\text {vs. } \mathrm{t}_{\text {PLH }}} \end{aligned}$ | 20 $25$ | $\begin{gathered} \pm 1 \\ 14 \end{gathered}$ $12$ | 25 | MHz <br> ns <br> ns <br> ns <br> $\mu \mathrm{s}$ |
| ISOLATION BARRIER RATING ${ }^{3}$ <br> Operating Isolation Voltage ( $\mathrm{V}_{\text {СМV }}$ ) <br> Isolation Rating Test Voltage $\left(\mathrm{V}_{\mathrm{CMV} \text { test }}\right)^{4}$ <br> Transient Immunity ( $\mathrm{V}_{\text {TRANSIENT }}$ ) <br> Isolation Mode Capacitance ( $\mathrm{C}_{\text {ISO }}$ ) <br> Capacitive Leakage Current ( $\mathrm{I}_{\text {LEAD }}$ ) | AD260A <br> AD260B <br> AD260A <br> AD260B <br> Total Capacitance, All Lines and Transformer 240 V rms @ 60 Hz | $\begin{aligned} & 1750 \\ & 3500 \\ & 10,000 \end{aligned}$ | 14 | $\begin{aligned} & 375 \\ & 1250 \\ & \\ & 18 \\ & 2 \end{aligned}$ | V rms <br> V rms <br> V rms <br> V rms <br> V/us <br> pF <br> $\mu \mathrm{A}$ rms |
| POWER TRANSFORMER <br> Primary Winding <br> Inductance (LP) <br> Number of Turns (NP) <br> Resistance <br> Max Volt-Seconds ( $\mathrm{E} \times \mathrm{t}$ ) <br> Recommended Operating Frequency <br> Absolute Min Operating Frequency <br> Secondary Winding <br> Number of Turns (NS) <br> Resistance <br> Insulation Withstand ( $\mathrm{V}_{\text {CMV TEST }}$ ) <br> Capacitance <br> Recommended Max Power | Bifilar Wound, Center-Tapped <br> Each Half <br> Each Half <br> Each Half <br> Each Half <br> $-25^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$, Push-Pull Drive <br> $-25^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$, Push-Pull Drive <br> Bifilar Wound, Center-Tapped <br> Each Half <br> Each Half <br> Primary to Secondary <br> Primary to Secondary <br> Rated Performance | $150$ <br> 75 <br> 3,500 <br> 1.0 | $\begin{aligned} & 1 \\ & 26 \\ & 0.6 \\ & 200 \end{aligned}$ | 27 <br> 300 <br> 1.5 | mH <br> Turns <br> $\Omega$ <br> $\mathrm{V} \times \mu \mathrm{s}$ <br> kHz <br> kHz <br> Turns <br> $\Omega$ <br> V rms <br> pF <br> W |
| POWER SUPPLY <br> Supply Voltage ( $+5 \mathrm{~V} \mathrm{dc}_{\mathrm{SYS}}$ and $+5 \mathrm{~V} \mathrm{dc}_{\text {FLD }}$ ) <br> Power Dissipation Capacitance <br> Quiescent Supply Current Supply Current | Rated Performance <br> Operating <br> Effective, per Input, Either Side <br> Effective per Output, Either Side-No Load <br> Each, +5 V dc ${ }_{\text {SYS }} \&$ FLD <br> All Lines @ 10 MHz (Sum of $+5 \mathrm{~V} \mathrm{dc}_{\text {SYS \& FLD }}$ ) | $\begin{aligned} & 4.5 \\ & 4.0 \end{aligned}$ | $\begin{aligned} & 8 \\ & 28 \\ & 4 \\ & 18 \end{aligned}$ | $\begin{aligned} & 5.5 \\ & 5.75 \end{aligned}$ | V dc <br> V dc <br> pF <br> pF <br> mA <br> mA |
| TEMPERATURE RANGE <br> Rated Performance $\left(\mathrm{T}_{\mathrm{A}}\right)^{5}$ Storage ( $\mathrm{T}_{\mathrm{STG}}$ ) |  | $\begin{aligned} & -25 \\ & -40 \end{aligned}$ |  | $\begin{aligned} & +85 \\ & +85 \end{aligned}$ | $\begin{aligned} & { }^{\circ} \mathrm{C} \\ & { }^{\circ} \mathrm{C} \end{aligned}$ |

## NOTES

${ }^{1}$ For best performance, bypass +5 V dc supplies to com. at or near the device $(0.01 \mu \mathrm{~F}) .+5 \mathrm{~V}$ dc supplies are also internally bypassed with $0.05 \mu \mathrm{~F}$.
${ }^{2}$ As the supply voltage is applied to either side of the AD260, the internal circuitry will go into a power-up reset mode (all lines disabled) for about $30 \mu \mathrm{~s}$ after the point where +5 V dc SYS \& FLD
3"Operating" isolation voltage is derived from the Isolation Test Voltage in accordance with such methods as found in VDE-0883 wherein a device will be "hi-pot" tested at twice the operating voltage, plus one thousand volts. Partial discharge testing, with an acceptance threshold of 80 pC of discharge may be considered the same as a hi-pot test (but nondestructive).
${ }^{4}$ Partial Discharge at 80 pC THLD.
${ }^{5}$ Supply Current will increase slightly, but otherwise the unit will function within specification to $-40^{\circ} \mathrm{C}$.
Specifications are subject to change without notice.

## ABSOLUTE MAXIMUM RATINGS*

| Parameter | Conditions | Min | Typ | Max | Units |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Supply Voltage ( $+5 \mathrm{~V} \mathrm{dc} \mathrm{SYS}_{\text {\& FLD }}$ ) |  | -0.5 |  | +6.0 | V |
| DC Input Voltage ( $\mathrm{V}_{\text {IN max }}$ ) | Referred to $+5 \mathrm{~V} \mathrm{dc}_{\text {SYS }} \&$ FLD and 5 V RTN ${ }_{\text {SYS }}$ \& FLD Respectively | -0.5 |  | +0.5 | V |
| DC Output Voltage (V $\mathrm{O}_{\text {out max }}$ ) | Referred to $+5 \mathrm{~V}^{\text {RTN }}$ SYS \& FLD ${ }^{\text {and }} 5 \mathrm{~V}$ dc $\mathrm{SYS}_{\text {\& FLD }}$ Respectively | -0.5 |  | +0.5 | V |
| Clamp Diode Input Current ( $\mathrm{I}_{\text {IK }}$ ) | For $\mathrm{V}_{\mathrm{I}}<-0.5 \mathrm{~V}$ or $\mathrm{V}_{\mathrm{I}}>5 \mathrm{VRTN}_{\text {SYS \& FLD }}+0.5 \mathrm{~V}$ | -25 |  | +25 | mA |
| Clamp Diode Output Current ( $\mathrm{I}_{\mathrm{OK}}$ ) | For $\mathrm{V}_{\mathrm{O}}<-0.5 \mathrm{~V}$ or $\mathrm{V}_{\mathrm{O}}>5 \mathrm{VRTN}_{\text {SYS } ~ \& ~ F L D ~}+0.5 \mathrm{~V}$ | -25 |  | +25 | mA |
| Output DC Current, per Pin ( $\mathrm{I}_{\text {OUT }}$ ) |  | -25 |  | +25 | mA |
| DC Current, $\mathrm{V}_{\mathrm{CC}}$ or GND ( $\mathrm{I}_{\mathrm{CC}}$ or $\mathrm{I}_{\mathrm{GND}}$ ) |  | -50 |  | +50 | mA |
| Storage Temperature ( $\mathrm{T}_{\mathrm{STG}}$ ) |  | -40 |  | +85 | ${ }^{\circ} \mathrm{C}$ |
| Lead Temperature (Soldering, 10 sec ) |  |  |  | +300 | ${ }^{\circ} \mathrm{C}$ |
| Electrostatic Protection ( $\mathrm{V}_{\text {ESD }}$ ) | Per MIL-STD-883, Method 3015 | 4.5 | 5 |  | kV |

*Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum ratings for extended periods may effect device reliability.

## I/O CONFIGURATIONS AVAILABLE

The AD260 is available in several configurations. The choice of model is determined by the desired number of input vs. output lines. All models have identical footprints with the power and enable pins always being in the same locations.

PIN FUNCTION DESCRIPTIONS

| Pin | Mnemonic | Function |
| :---: | :---: | :---: |
| 1-5* | S0 Through S4 | Digital Xmt or Rcv from F0 Through F4 |
| 6 | $\overline{\text { ENABLE }_{\text {SYS }}}$ | System Output Enable/Three-State |
| 7 | $+5 \mathrm{Vdc}{ }_{\text {SYs }}$ | System Power Supply (+5 V dc Input) |
| 8 | $5 \mathrm{VRTN}_{\text {SYS }}$ | System Power Supply Common |
| 9-14 |  | Not Present On Unit |
| 15 | $5 \mathrm{VRTN}_{\text {FLD }}$ | Field Power Supply Common |
| 16 | $+5 \mathrm{Vdc}_{\text {FLD }}$ | Field Power Supply (+5 V Input) |
| 17 | $\mathrm{ENABLE}_{\text {FLD }}$ | Field Output Enable/Three-State |
| 18-22* | F0 Through F4 | Digital Xmt or Rcv from S0 Through S4 |

*Function of pin determined by model. Refer to Table I.
Caution: Use care in handling unit as contaminants on the bot-

## PIN CONFIGURATION


tom side of the unit or the circuit card to which it is mounted will lead to reduced breakdown voltage across the isolation barrier.

## ORDERING GUIDE

| Model Number | Description | Isolation Test Voltage | Package Description | Package Option |
| :--- | :--- | :--- | :--- | :--- |
| AD260AND-0 | 0 Inputs, 5 Outputs | 1.75 kV rms | Plastic DIP | ND-22 |
| AD260AND-1 | 1 Input, 4 Outputs | 1.75 kV rms | Plastic DIP | ND-22 |
| AD260AND-2 | 2 Inputs, 3 Outputs | 1.75 kV rms | Plastic DIP | ND-22 |
| AD260AND-3 | 3 Inputs, 2 Outputs | 1.75 kV rms | Plastic DIP | ND-22 |
| AD260AND-4 | 4 Inputs, 1 Output | 1.75 kV rms | Plastic DIP | ND-22 |
| AD260AND-5 | 5 Inputs, 0 Outputs | 1.75 kV rms | Plastic DIP | ND-22 |
| AD260BND-0 | 0 Inputs, 5 Outputs | 3.5 kV rms | Plastic DIP | ND-22 |
| AD260BND-1 | 1 Input, 4 Outputs | 3.5 kV rms | Plastic DIP | ND-22 |
| AD260BND-2 | 2 Inputs, 3 Outputs | 3.5 kV rms | Plastic DIP | ND-22 |
| AD260BND-3 | 3 Inputs, 2 Outputs | 3.5 kV rms | Plastic DIP | ND-22 |
| AD260BND-4 | 4 Inputs, 1 Output | 3.5 kV rms | Plastic DIP | ND-22 |
| AD260BND-5 | 5 Inputs, 0 Outputs | 3.5 kV rms | Plastic DIP |  |

## CAUTION

ESD (electrostatic discharge) sensitive device. Electrostatic charges as high as 4000 V readily accumulate on the human body and test equipment and can discharge without detection. Although the AD260 features proprietary ESD protection circuitry, permanent damage may occur on devices subjected to high energy electrostatic discharges. Therefore, proper ESD precautions are recommended to avoid performance degradation or loss of functionality.

## PIN CONFIGURATIONS

AD260BND-0


AD260BND-1


AD260BND-2


AD260BND-3


## PIN CONFIGURATIONS



Table I.

| Pin | AD260BND-0 | AD260BND-1 | AD260BND-2 | AD260BND-3 | AD260BND-4 | AD260BND-5 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | S0 (Xmt) | S0 (Xmt) | S0 (Xmt) | S0 (Xmt) | S0 (Xmt) | S0 (Rcv) |
| 2 | S1 (Xmt) | S1 (Xmt) | S1 (Xmt) | S1 (Xmt) | S1 (Rcv) | S1 (Rcv) |
| 3 | S2 (Xmt) | S2 (Xmt) | S2 (Xmt) | S2 (Rcv) | S2 (Rcv) | S2 (Rcv) |
| 4 | S3 (Xmt) | S3 (Xmt) | S3 (Rcv) | S3 (Rcv) | S3 (Rcv) | S3 (Rcv) |
| 5 | S4 (Xmt) | S4 (Rcv) | S4 (Rcv) | S4 (Rcv) | S4 (Rcv) | S4 (Rcv) |
| 6 | $\overline{\text { ENABLE }}_{\text {SYS }}$ | * | * | * | * | * |
| 7 | $+5 \mathrm{~V} \mathrm{dc}_{\text {SYS }}$ | $\star$ | * | $\star$ | $\star$ | $\star$ |
| 8 | $5 \mathrm{VRTN}_{\text {SYs }}$ | $\star$ | $\star$ | * | $\star$ | $\star$ |
| 9 | DRVA | $\star$ | $\star$ | * | * | * |
| 10 | DRVCT | $\star$ | $\star$ | $\star$ | $\star$ | $\star$ |
| 11 | DRVB | $\star$ | * | * | $\star$ | $\star$ |
| 12 | $\mathrm{PWRB}_{\text {FLD }}$ | $\star$ | $\star$ | * | * | * |
| 13 | PWRCT ${ }_{\text {FLD }}$ | $\star$ | $\star$ | $\star$ | * | $\star$ |
| 14 | PWRA ${ }_{\text {FLD }}$ | $\star$ | $\star$ | * | $\star$ | $\star$ |
| 15 | $5 \mathrm{VRTN}_{\text {FLD }}$ | * | * | * | * | * |
| 16 | $+5 \mathrm{~V} \mathrm{dc}_{\text {FLD }}$ | $\star$ | $\star$ | $\star$ | $\star$ | $\star$ |
| 17 | $\mathrm{ENABLE}_{\text {FLD }}$ | $\star$ | $\star$ | $\star$ | $\star$ | $\star$ |
| 18 | F0 (Rcv) | F0 (Rcv) | F0 (Rcv) | F0 (Rcv) | F0 (Rcv) | F0 (Xmt) |
| 19 | F1 (Rcv) | F1 (Rcv) | F1 (Rcv) | F1 (Rcv) | F1 (Xmt) | F1 (Xmt) |
| 20 | F2 (Rcv) | F2 (Rcv) | F2 (Rcv) | F2 (Xmt) | F2 (Xmt) | F2 (Xmt) |
| 21 | F3 (Rcv) | F3 (Rcv) | F3 (Xmt) | F3 (Xmt) | F3 (Xmt) | F3 (Xmt) |
| 22 | F4 (Rcv) | F4 (Xmt) | F4 (Xmt) | F4 (Xmt) | F4 (Xmt) | F4 (Xmt) |

[^0]
## AD260

## (Continued from page 1)

Integral Isolated Power: The AD260 includes an integral, uncommitted and flexible 1 Watt power transformer for developing isolated field power sources.
Field and System Enable Functions: Both the isolated and nonisolated sides of the AD260 have ENABLE pins that threestate all outputs. Upon reenabling these pins, all outputs are updated to reflect the current input logic level.
CE Certifiable: Simply by adding the external bypass capacitors at the supply pins, the AD260 can attain CE certification in most applications (to the EMC directive) and conformance to the low voltage (safety) directive is assured by the EN60950 certification.

## GENERAL ATTRIBUTES

The AD260 provides five HCMOS/ACMOS compatible isolated logic lines with $\geq 10 \mathrm{kV} / \mu \mathrm{s}$ common-mode transient immunity.
The case design and pin arrangement provides greater than 18 mm spacing between field and system side conductors, providing CSA/IS and IEC creepage spacing consistent with 750 V mains isolation.
The five unidirectional logic lines have six possible combinations of "ins" and "outs," or transmitter/receiver pairs; hence there are six AD260 part configurations (see Table I).
Each 20 MHz logic line has a Schmidt trigger input and a threestate output (on the other side of the isolation barrier) and 14 ns of propagation delay. A single enable pin on either side of the barrier causes all outputs on that side to go three-state and all inputs (driven pins) to ignore their inputs and retain their last known state.
Note: All unused logic inputs (1-5) should be tied either high or low, but not left floating.

Edge "fidelity," or the difference in propagation time for rising and falling edges, is typically less than $\pm 1 \mathrm{~ns}$.
Power consumption, unlike opto-isolators, is a function of operating frequency. Each logic line barrier driver requires about $160 \mu \mathrm{~A}$ per MHz and each receiver $40 \mu \mathrm{~A}$ per MHz plus, of course, 4 mA total idle current (each side). The supply current diminishes slightly with increasing temperature (about $-0.03 \% /{ }^{\circ} \mathrm{C}$ ).
The total capacitance spanning the isolation barrier is less than 10 pF .
The minimum width of a pulse that can be accurately coupled across the barrier is about 25 ns . Therefore the maximum square-wave frequency of operation is 20 MHz .
Logic information is sent across the barrier as "set-hi/set-lo" data that is derived from logic level transitions of the input. At power-up or after a fault condition, an output might not represent the state of the respective channel input to the isolator. An internal circuit operates in the background which interrogates all inputs about every $5 \mu \mathrm{~s}$ and in the absence of logic transitions, sends appropriate "set-hi" or "set-lo" data across the barrier.
Recovery time from a fault condition or at power-up is thus between $5 \mu \mathrm{~s}$ and $10 \mu \mathrm{~s}$.


Figure 1. Simplified Block Diagram


EFFECTIVE CIRCUIT MODEL FOR ONE ISOLATED LOGIC LINE


Figure 2. Typical Timing and Delay Models

The power transformer is designed to operate between 150 kHz and 250 kHz and will easily deliver more than 1 W of isolated power when driven push-pull ( 5 V ) on the system side. Different transformer tap, rectifier and regulator schemes will provide combinations of $\pm 5 \mathrm{~V}, 15 \mathrm{~V}, 24 \mathrm{~V}$ or even 30 V or higher. The output voltage when driven with a low voltage-drop drive (@) 5 V push-pull) will be 37 V p-p across the entire secondary. This will drop to 33 V p-p at 4.5 V drive.


Figure 3. System Side Transformer Driver Examples

## Application Examples

The following is an example of a typical transformer system-side drive circuit and a field-side regulation circuit suitable for use in most general applications.


Figure 4.


Figure 5. Field Side Power Supply Rectifier Examples

## OUTLINE DIMENSIONS

Dimensions shown in inches and (mm).


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- Подбор комплектации
- Индивидуальный подход
- Гибкое ценообразование
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[^0]:    $\star$ Pin function is the same on all models, as shown in the AD260BND-0 column.

