

SINGLE-ENDED ANALOG-INPUT 24-BIT, 96-kHz STEREO A/D CONVERTER

FEATURES

- 24-Bit Delta-Sigma Stereo A/D Converter
- Single-Ended Voltage Input: 3 V p-p
- Antialiasing Filter Included
- Oversampling Decimation Filter
 - Oversampling Frequency: $\times 64$, $\times 128$
 - Pass-Band Ripple: ± 0.05 dB
 - Stop-Band Attenuation: -65 dB
 - On-Chip High-Pass Filter (HPF): 0.84 Hz (44.1 kHz)
- High Performance
 - THD+N: 96 dB (Typical)
 - SNR: 105 dB (Typical)
 - Dynamic Range: 105 dB (Typical)
- PCM Audio Interface
 - Master/Slave Mode Selectable
 - Data Formats: 24-Bit Left-Justified; 24-Bit I^2S ; 20-, 24-Bit Right-Justified
- Sampling Rate: 16 kHz to 96 kHz
- System Clock: 256 f_s , 384 f_s , 512 f_s , 768 f_s
- Dual Power Supplies: 5 V for Analog, 3.3 V for Digital
- Package: 20-Pin SSOP

APPLICATIONS

- AV Amplifier Receiver
- MD Player
- CD Recorder
- Multitrack Receiver
- Electric Musical Instrument

DESCRIPTION

The PCM1802 is a high-performance, low-cost, single-chip stereo analog-to-digital converter with single-ended analog voltage input. The PCM1802 uses a delta-sigma modulator with 64- or 128-times oversampling, and includes a digital decimation filter and high-pass filter (HPF), which removes the dc component of the input signal. For various applications, the PCM1802 supports master and slave modes and four data formats in serial interface. The PCM1802 is suitable for a wide variety of cost-sensitive consumer applications where good performance, 5-V analog supply, and 3.3-V digital supply operation is required. The PCM1802 is fabricated using a highly advanced CMOS process and is available in the DB 20-pin SSOP package.



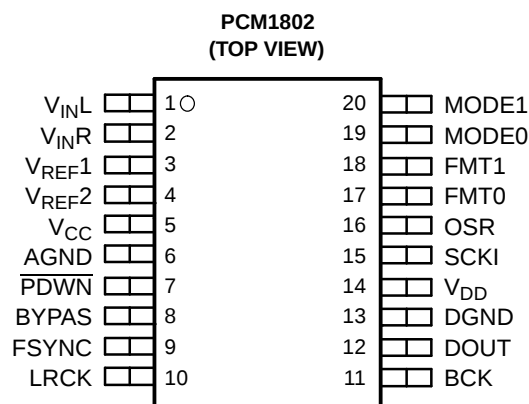
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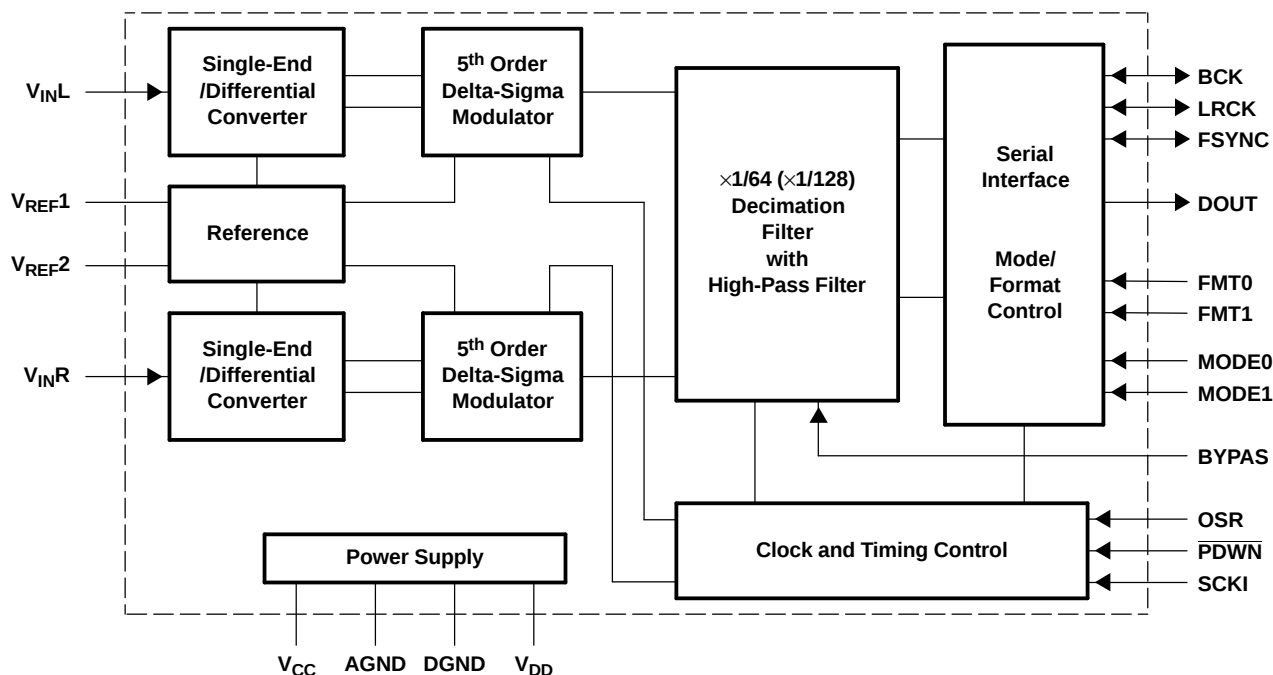
This device contains circuits to protect its inputs and outputs against damage due to high static voltages or electrostatic fields. These circuits have been qualified to protect this device against electrostatic discharges (ESD) of up to 2 kV according to MIL-STD-883C, Method 3015; however, it is advised that precautions be taken to avoid application of any voltage higher than maximum-rated voltages to these high-impedance circuits. During storage or handling, the device leads should be shorted together or the device should be placed in conductive foam. In a circuit, unused inputs should always be connected to an appropriated logic voltage level, preferably either V_{CC} or ground. Specific guidelines for handling devices of this type are contained in the publication *Electrostatic Discharge (ESD)* ([SSYA010](#)) available from Texas Instruments.

PIN ASSIGNMENTS



P0009-02

BLOCK DIAGRAM



B0004-07

Terminal Functions

TERMINAL NAME	PIN	I/O	DESCRIPTIONS
AGND	6	—	Analog GND
BCK	11	I/O	Bit clock input/output ⁽¹⁾
BYPAS	8	I	HPF bypass control. Low: normal mode (dc cut); High: bypass mode (through) ⁽²⁾
DGND	13	—	Digital GND
DOUT	12	O	Audio data output
FMT0	17	I	Audio data format select 0. See <i>data format</i> ⁽²⁾
FMT1	18	I	Audio data format select 1. See <i>data format</i> ⁽²⁾
FSYNC	9	I/O	Frame synchronous clock input/output ⁽¹⁾
LRCK	10	I/O	Sampling clock input/output ⁽¹⁾
MODE0	19	I	Mode select 0. See <i>interface mode</i> ⁽²⁾
MODE1	20	I	Mode select 1. See <i>interface mode</i> ⁽²⁾
OSR	16	I	Oversampling ratio select. Low: $\times 64 f_s$; High: $\times 128 f_s$ ⁽²⁾
$\overline{\text{PDWN}}$	7	I	Power-down control, active-low ⁽²⁾
SCKI	15	I	System clock input; 256 f_s , 384 f_s , 512 f_s , or 768 f_s ⁽³⁾
V _{CC}	5	—	Analog power supply, 5 V
V _{DD}	14	—	Digital power supply, 3.3 V
V _{INL}	1	I	Analog input, L-channel
V _{INR}	2	I	Analog input, R-channel
V _{REF1}	3	—	Reference-1 decoupling capacitor
V _{REF2}	4	—	Reference-2 voltage input, normally connected to V _{CC}

(1) Schmitt-trigger input

(2) Schmitt-trigger input with internal pulldown (50 k Ω typically), 5-V tolerant

(3) Schmitt-trigger input, 5-V tolerant

ABSOLUTE MAXIMUM RATINGS

over operating free-air temperature range (unless otherwise noted)⁽¹⁾

Supply voltage	V _{CC}	6.5 V
	V _{DD}	4 V
Ground voltage differences	AGND, DGND	± 0.1 V
Supply voltage difference	V _{CC} , V _{DD}	V _{CC} – V _{DD} < 3.0 V
Digital input voltage	FSYNC, LRCK, BCK, DOUT	–0.3 V to (V _{DD} + 0.3 V)
	$\overline{\text{PDWN}}$, BYPAS, SCKI, OSR, FMT0, FMT1, MODE0, MODE1	–0.3 V to 6.5 V
Analog input voltage	V _{INL} , V _{INR} , V _{REF1} , V _{REF2}	–0.3 V to (V _{CC} + 0.3 V)
Input current (any pins except supplies)		± 10 mA
Ambient temperature under bias		–40°C to 125°C
Storage temperature		–55°C to 150°C
Junction temperature		150°C
Lead temperature (soldering)		260°C, 5 s
Package temperature (IR reflow, peak)		260°C

(1) Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

ELECTRICAL CHARACTERISTICS

all specifications at $T_A = 25^\circ\text{C}$, $V_{CC} = 5\text{ V}$, $V_{DD} = 3.3\text{ V}$, master mode, $f_S = 44.1\text{ kHz}$, system clock = $384 f_S$, oversampling ratio = $\times 128$, 24-bit data (unless otherwise noted)

		TEST CONDITIONS	PCM1802DB			UNIT
			MIN	TYP	MAX	
Resolution			24			Bits
DATA FORMAT						
Audio data interface format			Left-justified, I ² S, right-justified			
Audio data bit length			20, 24			Bits
Audio data format			MSB first, 2s complement			
f _S	Sampling frequency		16	44.1	96	kHz
System clock frequency		256 f _S	4.096	11.2896	24.576	MHz
		384 f _S	6.144	16.9344	36.864	
		512 f _S	8.192	22.5792	49.152	
		768 f _S	12.288	33.8688	(1)	
INPUT LOGIC						
V _{IH} ⁽²⁾	Input logic level		2		V _{DD}	VDC
V _{IL} ⁽²⁾			0		0.8	
V _{IH} ⁽³⁾			2		5.5	
V _{IL} ⁽³⁾			0		0.8	
I _{IH} ⁽⁴⁾	Input logic current	V _{IN} = V _{DD}			±10	μA
I _{IL} ⁽⁴⁾		V _{IN} = 0 V			±10	
I _{IH} ⁽⁵⁾		V _{IN} = V _{DD}		65	100	
I _{IL} ⁽⁵⁾		V _{IN} = 0 V			±10	
OUTPUT LOGIC						
V _{OH} ⁽⁶⁾	Output logic level	I _{OUT} = −1 mA	2.8			VDC
V _{OL} ⁽⁶⁾		I _{OUT} = 1 mA			0.5	
DC ACCURACY						
Gain mismatch, channel-to-channel			±1	±4		%FSR
Gain error			±2	±6		%FSR
Bipolar zero error		HPF bypassed ⁽⁷⁾	±2			%FSR
DYNAMIC PERFORMANCE ⁽⁸⁾						
THD+N Total harmonic distortion + noise	f _S = 44.1 kHz, V _{IN} = −0.5 dB		0.0015%	0.003%		
	f _S = 96 kHz, V _{IN} = −0.5 dB ⁽⁹⁾		0.0025%			
	f _S = 44.1 kHz, V _{IN} = −60 dB		0.7%			
	f _S = 96 kHz, V _{IN} = −60 dB ⁽⁹⁾		1.2%			
Dynamic range	f _S = 44.1 kHz, A-weighted		100	105		dB
	f _S = 96 kHz, A-weighted ⁽⁹⁾			103		
S/N ratio	f _S = 44.1 kHz, A-weighted		100	105		dB
	f _S = 96 kHz, A-weighted ⁽⁹⁾			103		

(1) Maximum system clock frequency is not applicable at $768 f_S$, $f_S = 96\text{ kHz}$. See the *System Clock* section of this data sheet.

(2) Pins 9–11: FSYNC, LRCK, BCK (Schmitt-trigger input in slave mode)

(3) Pins 7–8, 15–20: $\overline{\text{PDWN}}$, BYPAS, SCKI, OSR, FMT0, FMT1, MODE0, MODE1 (Schmitt-trigger input, 5-V tolerant)

(4) Pins 9–11, 15: FSYNC, LRCK, BCK (Schmitt-trigger input in slave mode), SCKI (Schmitt-trigger input)

(5) Pins 7–8, 16–20: $\overline{\text{PDWN}}$, BYPAS, OSR, FMT0, FMT1, MODE0, MODE1 (Schmitt-trigger input, with 50-k Ω typical pulldown resistor)

(6) Pins 9–12: FSYNC, LRCK, BCK (in master mode), DOUT

(7) High-pass filter

(8) Analog performance specifications are tested with System Two™ audio measurement system by Audio Precision™, using 400-Hz HPF, 20-kHz LPF for 44.1-kHz operation, 40-kHz LPF for 96-kHz operation in RMS mode.

(9) $f_S = 96\text{ kHz}$, system clock = $256 f_S$, oversampling ratio = $\times 64$.

ELECTRICAL CHARACTERISTICS (continued)

all specifications at $T_A = 25^\circ\text{C}$, $V_{CC} = 5\text{ V}$, $V_{DD} = 3.3\text{ V}$, master mode, $f_S = 44.1\text{ kHz}$, system clock = $384 f_S$, oversampling ratio = $\times 128$, 24-bit data (unless otherwise noted)

		TEST CONDITIONS	PCM1802DB			UNIT
			MIN	TYP	MAX	
Channel separation		f _S = 44.1 kHz	96	103	dB	
		f _S = 96 kHz ⁽⁹⁾	98			
ANALOG INPUT						
Input voltage			0.6 V _{CC}		Vp-p	
Center voltage (V _{REF1})			0.5 V _{CC}		V	
Input impedance			20		kΩ	
Antialiasing filter frequency response		−3 dB	300		kHz	
DIGITAL FILTER PERFORMANCE						
Pass band			0.454 f _S		Hz	
Stop band			0.583 f _S		Hz	
Pass-band ripple			±0.05		dB	
Stop-band attenuation			−65		dB	
Delay time			17.4/f _S		s	
HPF frequency response		−3 dB	0.019 f _S		mHz	
POWER SUPPLY REQUIREMENTS						
V _{CC}	Voltage range		4.5	5	5.5	VDC
V _{DD}			2.7	3.3	3.6	
I _{CC}	Supply current ⁽¹⁰⁾	V _{CC} = 5 V, V _{DD} = 3.3 V	24		30	mA
I _{DD}		f _S = 44.1 kHz V _{CC} = 5 V, V _{DD} = 3.3 V	8.3		10	
		f _S = 96 kHz, V _{CC} = 5 V, V _{DD} = 3.3 V ⁽⁸⁾	17			
P _D	Power dissipation; operation	f _S = 44.1 kHz, V _{CC} = 5 V, V _{DD} = 3.3 V	147		183	mW
		f _S = 96 kHz, V _{CC} = 5 V, V _{DD} = 3.3 V ⁽⁸⁾	176			
	Power dissipation; power down	V _{CC} = 5 V, V _{DD} = 3.3 V	0.5			mW
TEMPERATURE RANGE						
Operation temperature			−40		85	°C
Thermal resistance (θ _{JA})		20-pin SSOP	115			°C/W

(10) Minimum load on DOUT (pin 12), BCK (pin 11), LRCK (pin 10), FSYNC (pin 9)

TYPICAL PERFORMANCE CURVES OF INTERNAL FILTER

Digital Filter—Decimation Filter Frequency Response

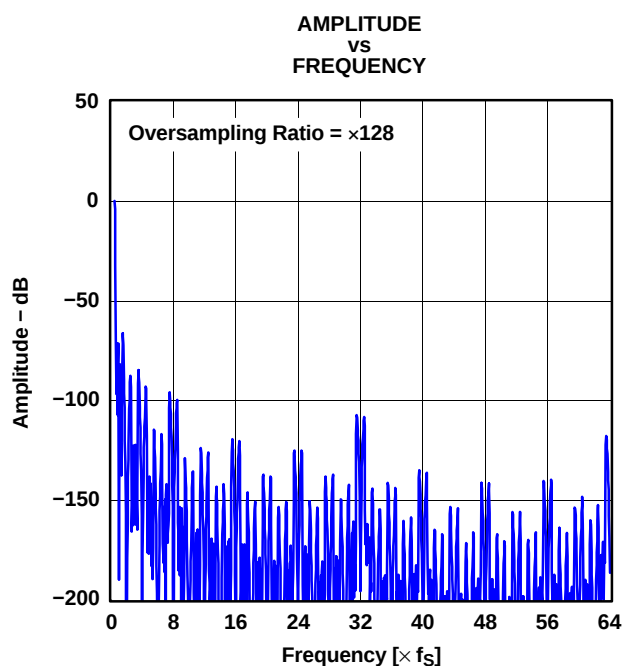


Figure 1. Overall Characteristics

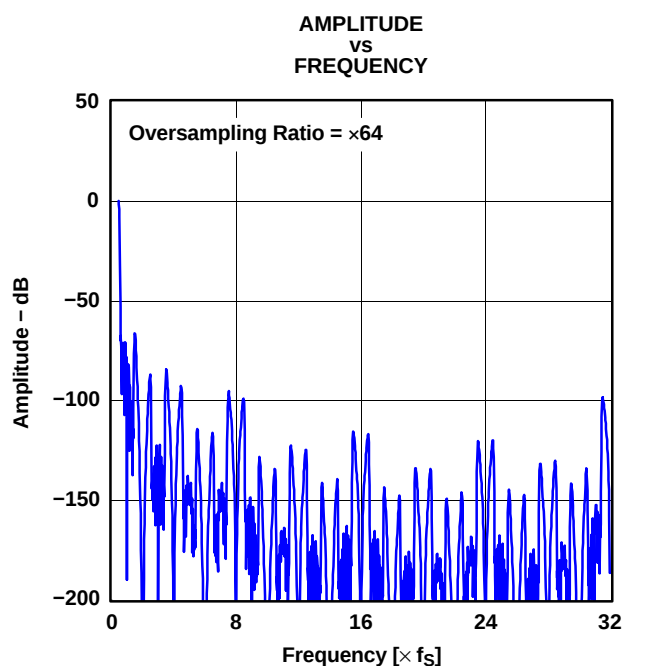


Figure 2. Overall Characteristics

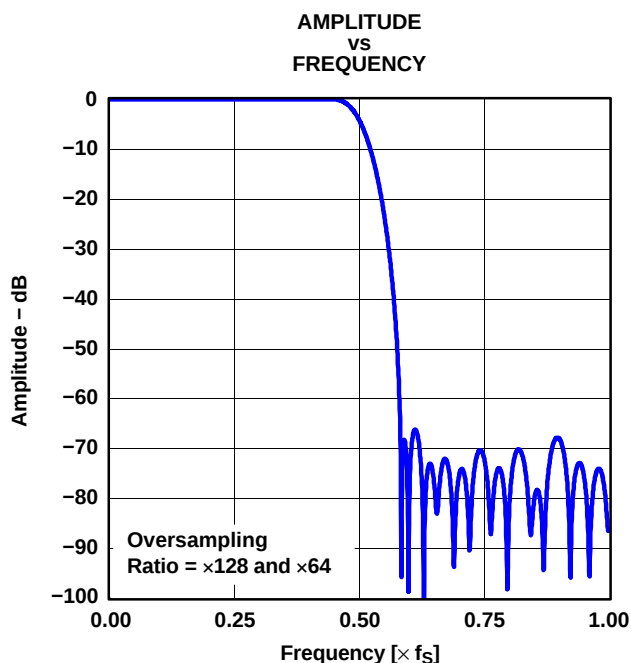


Figure 3. Stop-Band Attenuation Characteristics

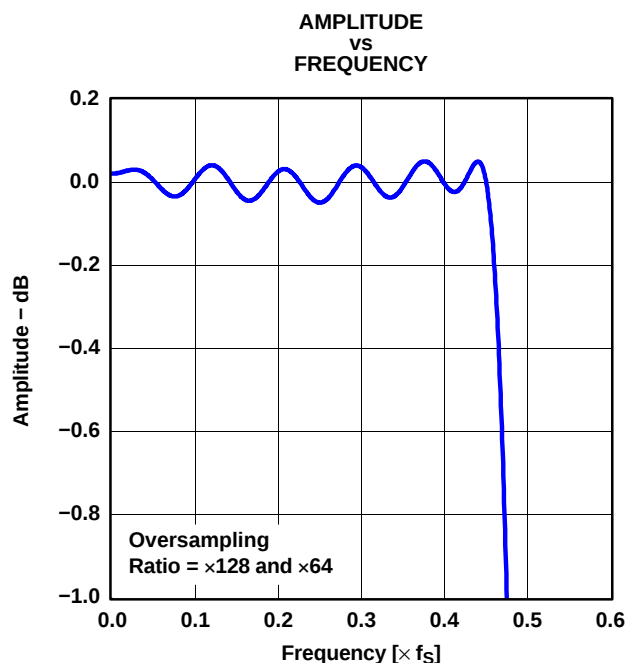


Figure 4. Pass-Band Ripple Characteristics

All specifications at $T_A = 25^\circ\text{C}$, $V_{CC} = 5\text{ V}$, $V_{DD} = 3.3\text{ V}$, master mode, $f_S = 44.1\text{ kHz}$, system clock = $384 f_S$, oversampling ratio = $\times 128$, 24-bit data, unless otherwise noted.

TYPICAL PERFORMANCE CURVES OF INTERNAL FILTER (continued)

HPF (High-Pass Filter) Frequency Response

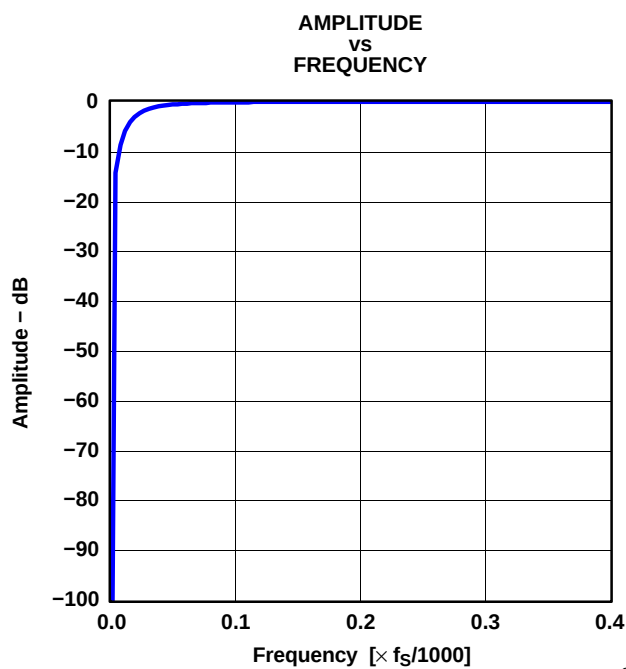


Figure 5. HPF Stop-Band Characteristics

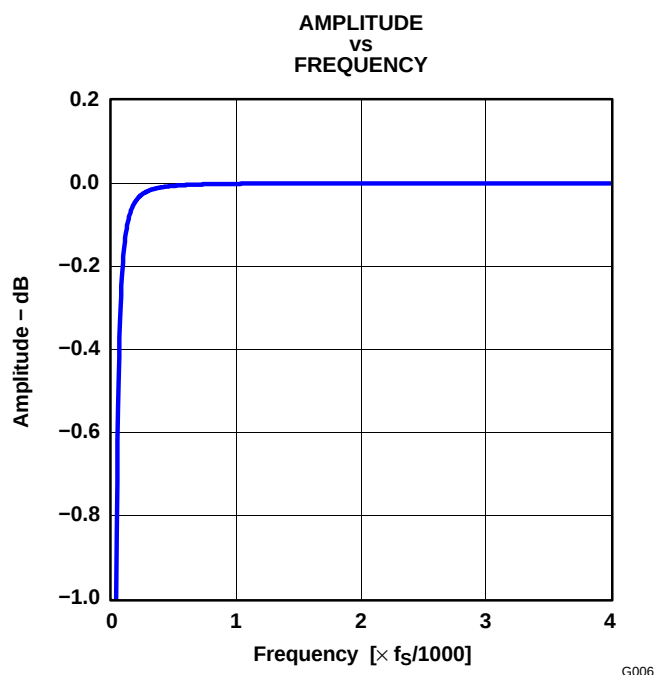


Figure 6. HPF Pass-Band Characteristics

Analog Filter—Antialiasing Filter Frequency Response

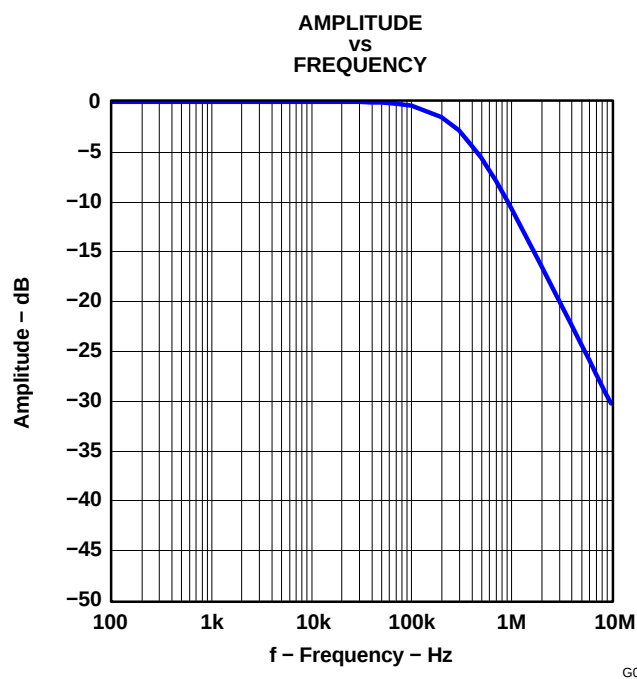


Figure 7. Antialias Filter Stop-Band Characteristics

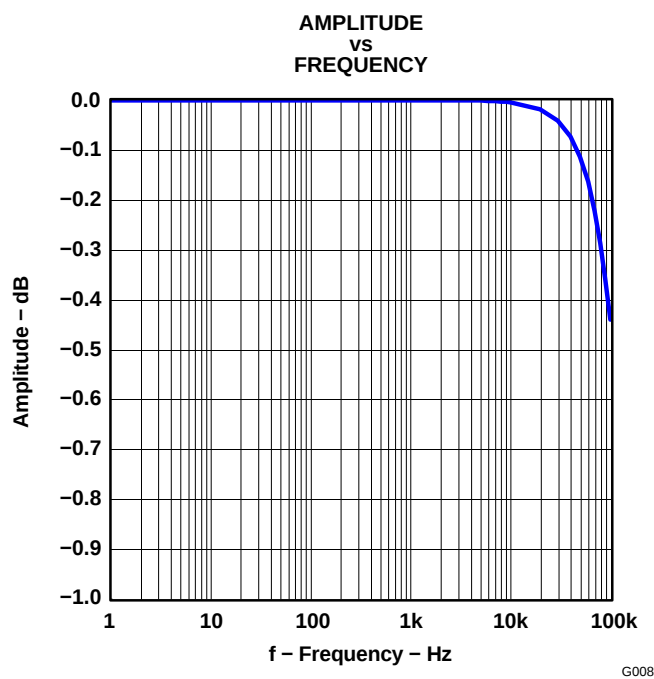


Figure 8. Antialias Filter Pass-Band Characteristics

All specifications at $T_A = 25^\circ\text{C}$, $V_{CC} = 5\text{ V}$, $V_{DD} = 3.3\text{ V}$, master mode, $f_S = 44.1\text{ kHz}$, system clock = $384 f_S$, oversampling ratio = $\times 128$, 24-bit data, unless otherwise noted.

TYPICAL PERFORMANCE CURVES

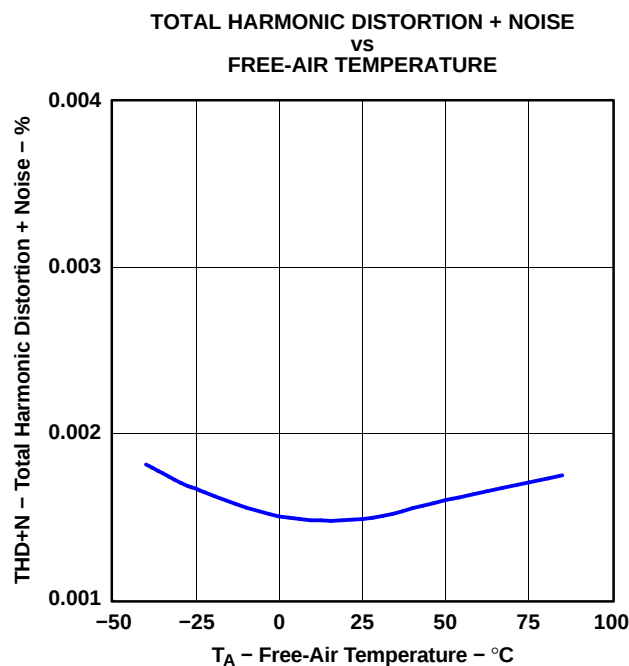


Figure 9.

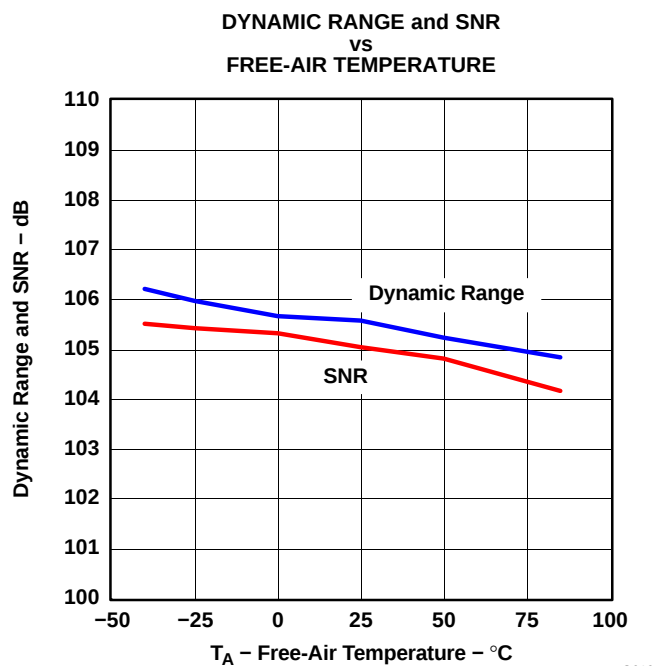


Figure 10.

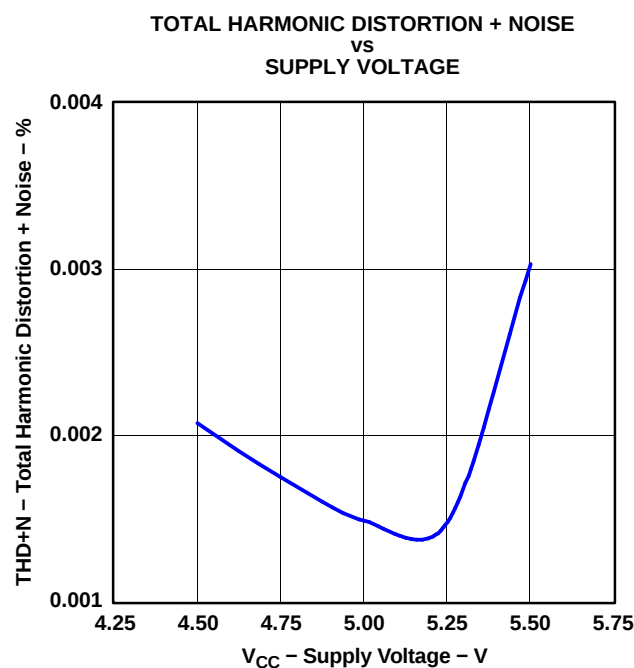


Figure 11.

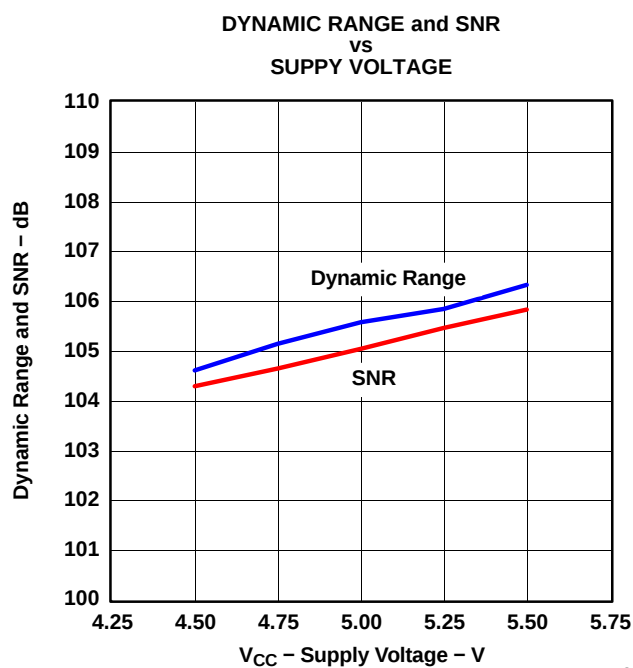


Figure 12.

All specifications at T_A = 25°C, V_{CC} = 5 V, V_{DD} = 3.3 V, master mode, f_S = 44.1 kHz, system clock = 384 f_S, oversampling ratio = ×128, 24-bit data, unless otherwise noted.

TYPICAL PERFORMANCE CURVES (continued)

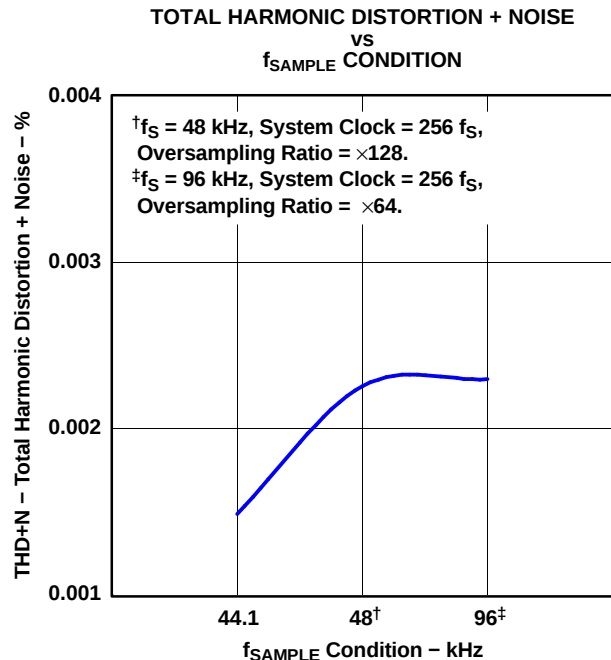


Figure 13.

G013

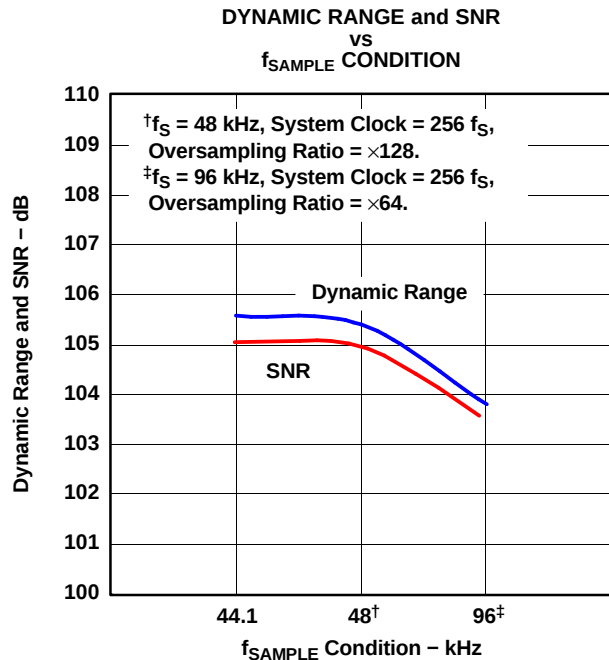


Figure 14.

G014

Output Spectrum

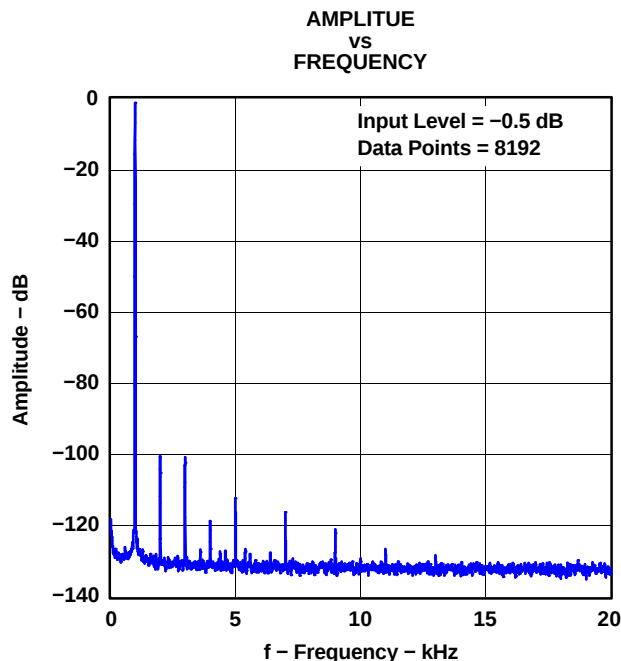


Figure 15.

G015

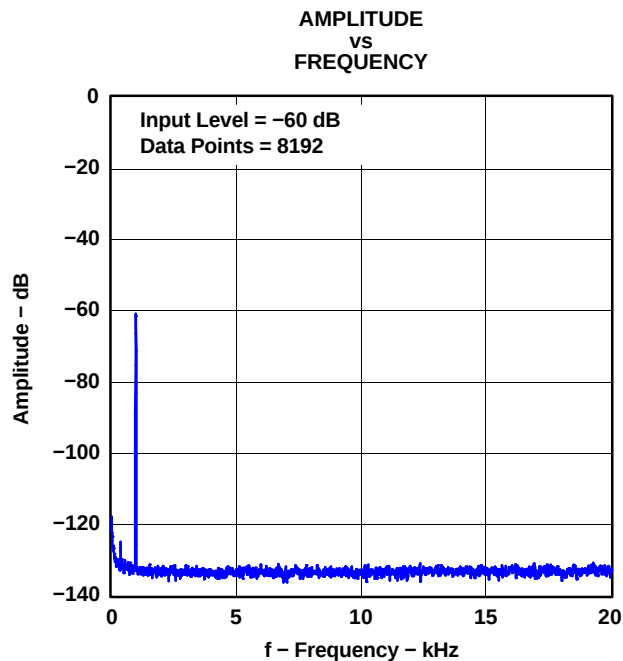
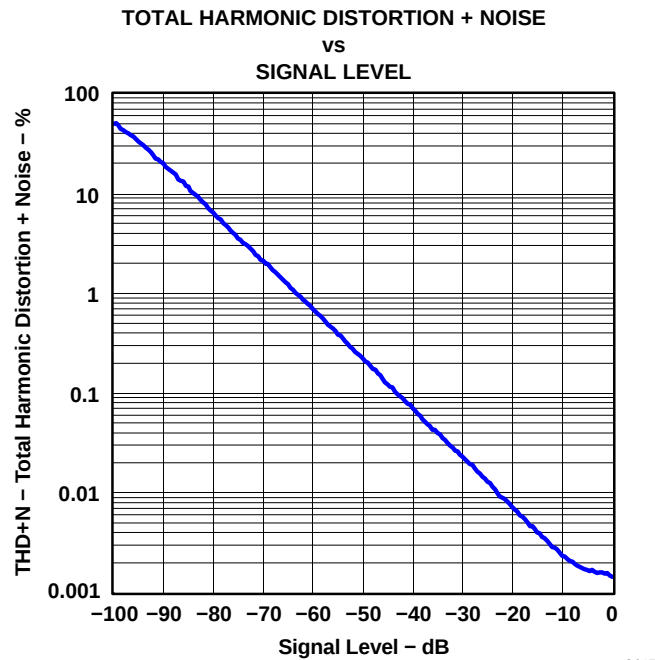


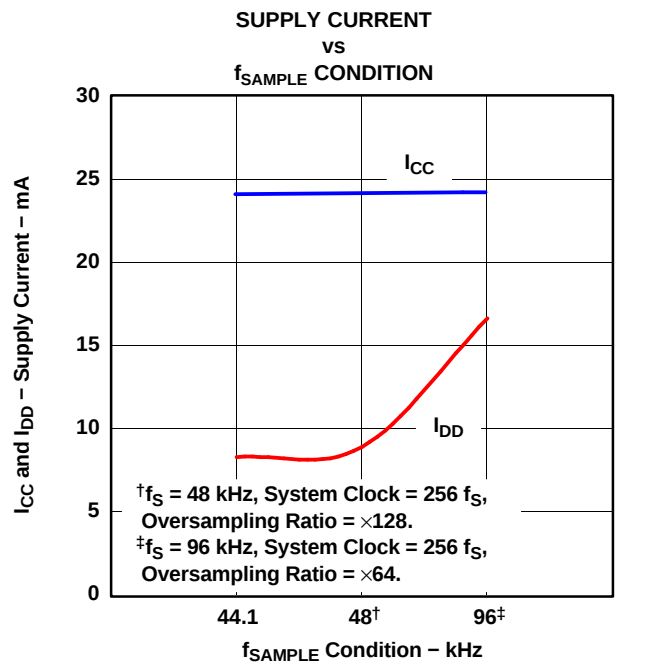
Figure 16.

G016

All specifications at T_A = 25°C, V_{CC} = 5 V, V_{DD} = 3.3 V, master mode, f_S = 44.1 kHz, system clock = 384 f_S, oversampling ratio = ×128, 24-bit data, unless otherwise noted.

TYPICAL PERFORMANCE CURVES (continued)

G017

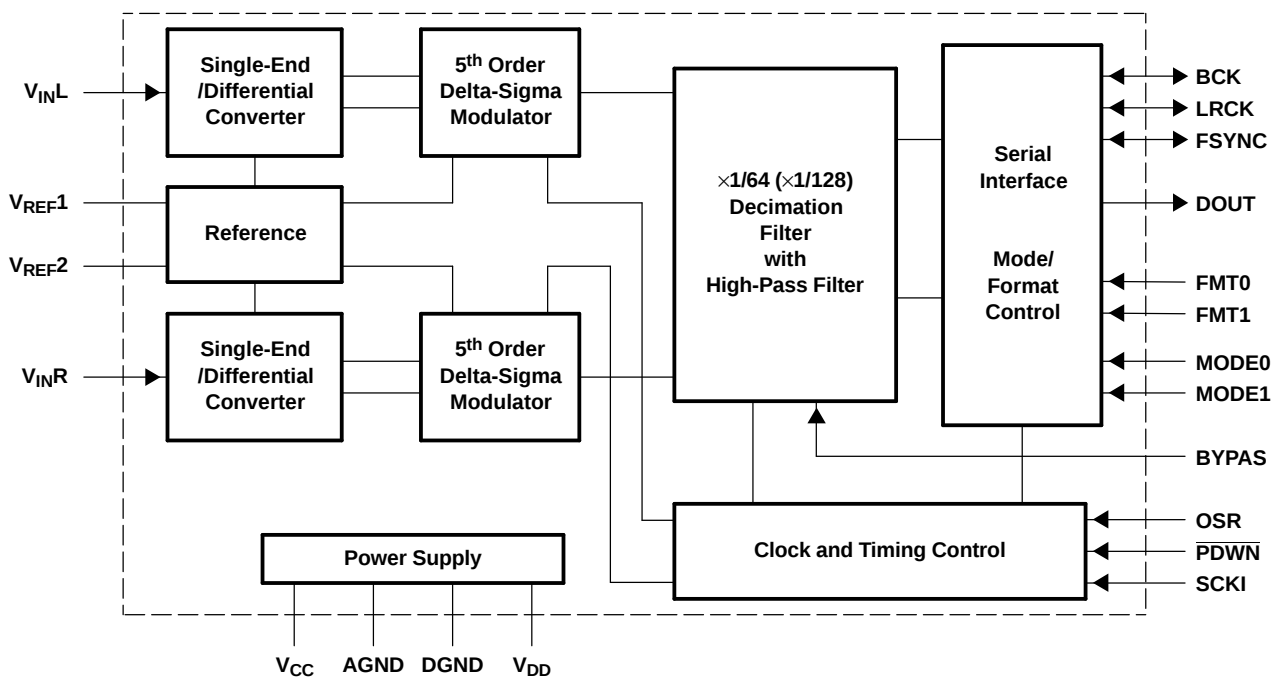
Supply Current

G018

All specifications at $T_A = 25^\circ\text{C}$, $V_{CC} = 5\text{ V}$, $V_{DD} = 3.3\text{ V}$, master mode, $f_S = 44.1\text{ kHz}$, system clock = $384 f_S$, oversampling ratio = $\times 128$, 24-bit data, unless otherwise noted.

PRINCIPLES OF OPERATION

The PCM1802 consists of a reference circuit, two channels of single-ended-to-differential converter, a fifth-order delta-sigma modulator with full differential architecture, a decimation filter with high-pass filter, and a serial interface circuit. Figure 19 illustrates the total architecture of the PCM1802, Figure 20 illustrates the architecture of single-ended-to-differential converter and antialiasing filter, and Figure 21 is the block diagram of the fifth-order delta-sigma modulator and transfer function. An on-chip high-precision reference with one external capacitor provides all reference voltages that are needed in the PCM1802 and defines the full-scale voltage range for both channels. On-chip single-ended-to-differential signal converters save the design, space, and extra parts cost for external signal converters. Full-differential architecture provides a wide dynamic range and excellent power-supply rejection performance. The input signal is sampled at a $\times 64$ or $\times 128$ oversampling rate, thus eliminating an external sample-hold amplifier. A fifth-order delta-sigma noise shaper, which consists of five integrators using the switched capacitor technique and a comparator, shapes the quantization noise generated by the comparator and 1-bit DAC outside of the audio signal band. The high-order delta-sigma modulation randomizes the modulator outputs and reduces the idle tone level. The $64\text{-}f_s$ or $128\text{-}f_s$, 1-bit stream from the delta-sigma modulator is converted to a $1\text{-}f_s$, 24-bit or 20-bit digital signal by removing high-frequency noise components with a decimation filter. The dc component of the signal is removed by the HPF, and the HPF output is converted to a time-multiplexed serial signal through the serial interface, which provides flexible serial formats.



B0004-07

Figure 19. Block Diagram



Block diagram of a 5th-order sigma-delta modulator. The diagram shows a cascade of five SW-CAP Integrators. The input $X(z)$ is summed with a feedback signal from a 1-bit DAC to enter the first integrator. The output of each integrator is summed with a feedback signal from a common summing junction before entering the next integrator. The output of the fifth integrator is summed with a quantization noise signal $Q_n(z)$ and then passed through a comparator to produce the digital output $Y(z)$. The digital output $Y(z)$ is also fed back through the 1-bit DAC to the input summing junction. The overall transfer function is given as $Y(z) = \text{STF}(z) * X(z) + \text{NTF}(z) * Q_n(z)$, with $\text{STF}(z) = H(z) / [1 + H(z)]$ and $\text{NTF}(z) = 1 / [1 + H(z)]$.

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PRINCIPLES OF OPERATION (continued)

System Clock

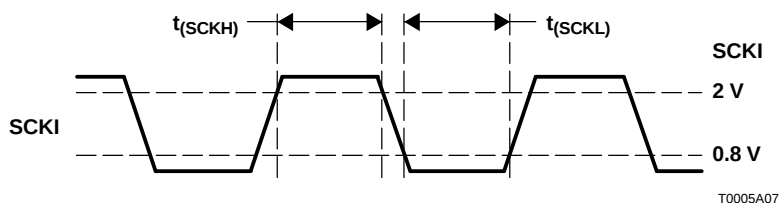
The PCM1802 supports $256 f_s$, $384 f_s$, $512 f_s$, and $768 f_s$ as the system clock, where f_s is the audio sampling frequency. The system clock must be supplied on SCKI (pin 15).

The PCM1802 has a system clock detection circuit which automatically senses if the system clock is operating at $256 f_s$, $384 f_s$, $512 f_s$, or $768 f_s$ in slave mode. In master mode, the system clock frequency must be selected by MODE0 (pin 19) and MODE1 (pin 20), and $768 f_s$ is not available. For system clock inputs of $384 f_s$, $512 f_s$, and $768 f_s$, the system clock is divided to $256 f_s$ automatically, and the $256 f_s$ clock is used to operate the delta-sigma modulator and the digital filter.

Table 1 shows the relationship of typical sampling frequencies and system clock frequencies, and Figure 22 shows system clock timing.

Table 1. Sampling Frequency and System Clock Frequency

SAMPLING RATE FREQUENCY (kHz)	SYSTEM CLOCK FREQUENCY (MHz)			
	$256 f_s$	$384 f_s$	$512 f_s$	$768 f_s$
32	8.192	12.288	16.384	24.576
44.1	11.2896	16.9344	22.5792	33.8688
48	12.288	18.432	24.576	36.864
64	16.384	24.576	32.768	49.152
88.2	22.5792	33.8688	45.1584	—
96	24.576	36.864	49.152	—



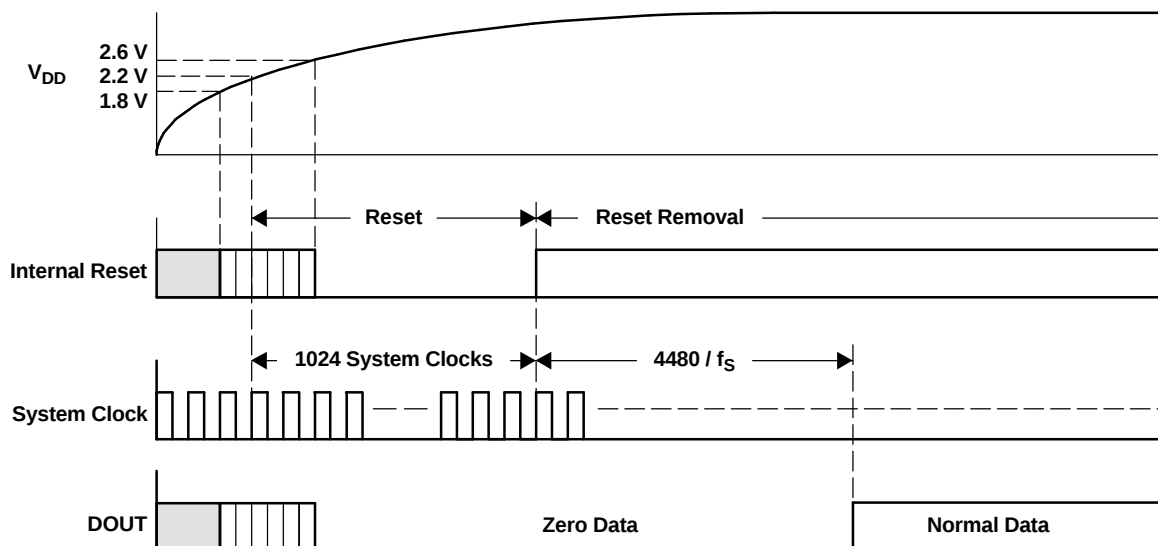
T0005A07

PARAMETER		MIN	MAX	UNIT
$t_{(SCKH)}$	System clock-pulse duration, high	7		ns
$t_{(SCKL)}$	System clock-pulse duration, low	7		ns

Figure 22. System Clock Timing

Power-On Reset Sequence

The PCM1802 has an internal power-on reset circuit, and initialization (reset) is performed automatically when the power supply (V_{DD}) exceeds 2.2 V (typical). While $V_{DD} < 2.2$ V (typical), and for 1024 system-clock counts after $V_{DD} > 2.2$ V (typical), the PCM1802 stays in the reset state and the digital output is forced to zero. The digital output is valid after the reset state is released and the time of $4480/f_S$ has passed. Figure 23 illustrates the internal power-on reset timing and the digital output for power-on reset.



T0014-05

Figure 23. Internal Power-On Reset Timing

Serial Audio Data Interface

The PCM1802 interfaces with the audio system through BCK (pin 11), LRCK (pin 10), FSYNC (pin 9), and DOUT (pin 12).

Interface Mode

The PCM1802 supports master mode and slave mode as interface modes, and they are selected by MODE1 (pin 20) and MODE0 (pin 19) as shown in Table 2.

In master mode, the PCM1802 provides the timing for serial audio data communications between the PCM1802 and the digital audio processor or external circuit. In slave mode, the PCM1802 receives the timing for data transfer from an external controller.

Table 2. Interface Mode

MODE1	MODE0	INTERFACE MODE
0	0	Slave mode (256 f _S , 384 f _S , 512 f _S , 768 f _S)
0	1	Master mode (512 f _S)
1	0	Master mode (384 f _S)
1	1	Master mode (256 f _S)

Master mode

In master mode, BCK, LRCK, and FSYNC work as output pins, and these pins are controlled by timing which is generated in the clock circuit of the PCM1802. FSYNC is used to designate the valid data from the PCM1802. The rising edge of FSYNC indicates the starting point of the converted audio data and the falling edge of this signal indicates the ending point of the data. The frequency of this signal is fixed at $2 \times \text{LRCK}$. The duty cycle ratio depends on data bit length. The frequency of BCK is fixed at $64 \times \text{LRCK}$. The 768 f_S system clock is not available in master mode.

Slave mode

In slave mode, BCK, LRCK, and FSYNC work as input pins. FSYNC is used to enable the BCK signal, and the PCM1802 can shift out the converted data while FSYNC is HIGH. The PCM1802 accepts either the 64 BCK/LRCK or the 48 BCK/LRCK format. The delay of FSYNC from the LRCK transition must be within 16 BCKs for the 64 BCK/LRCK format and within 12 BCKs for the 48 BCK/LRCK format.

Data Format

The PCM1802 supports four audio data formats in both master and slave modes, and they are selected by FMT1 (pin 18) and FMT0 (pin 17) as shown in Table 3. Figure 24 and Figure 26 illustrate the data formats in slave mode and master mode, respectively.

Table 3. Data Format

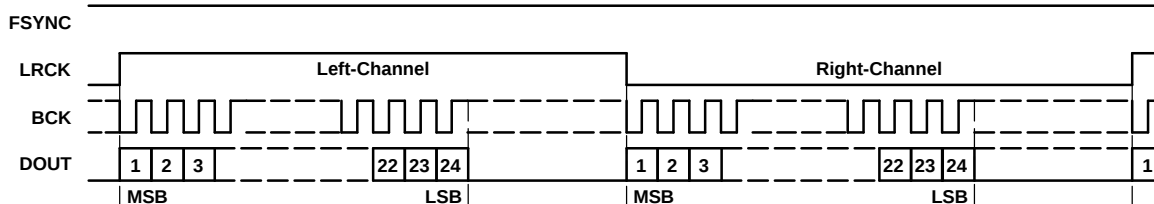
FORMAT#	FMT1	FMT0	FORMAT
0	0	0	Left-justified, 24-bit
1	0	1	I ² S, 24-bit
2	1	0	Right-justified, 24-bit
3	1	1	Right-justified, 20-bit

Interface Timing

Figure 25 and Figure 27 illustrate the interface timing in slave mode and master mode, respectively.

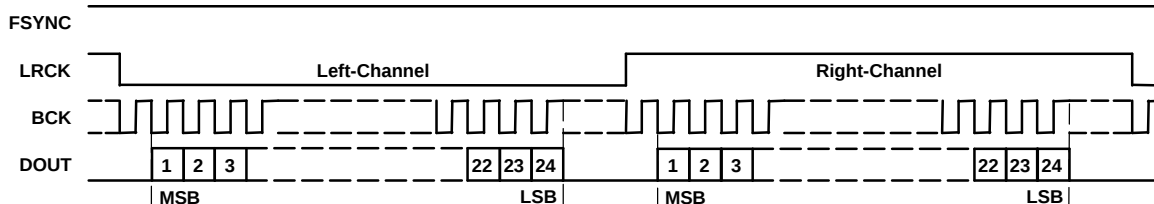
FORMAT 0: FMT[1:0] = 00

24-Bit, MSB-First, Left-Justified



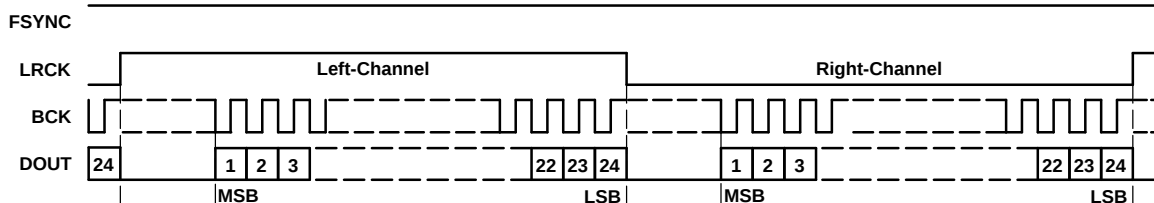
FORMAT 1: FMT[1:0] = 01

24-Bit, MSB-First, I²S



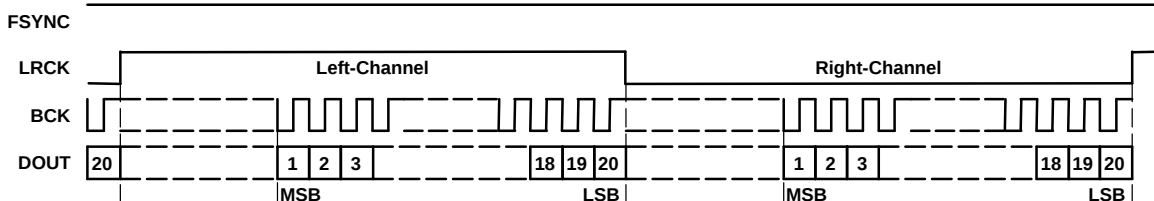
FORMAT 2: FMT[1:0] = 10

24-Bit, MSB-First, Right-Justified



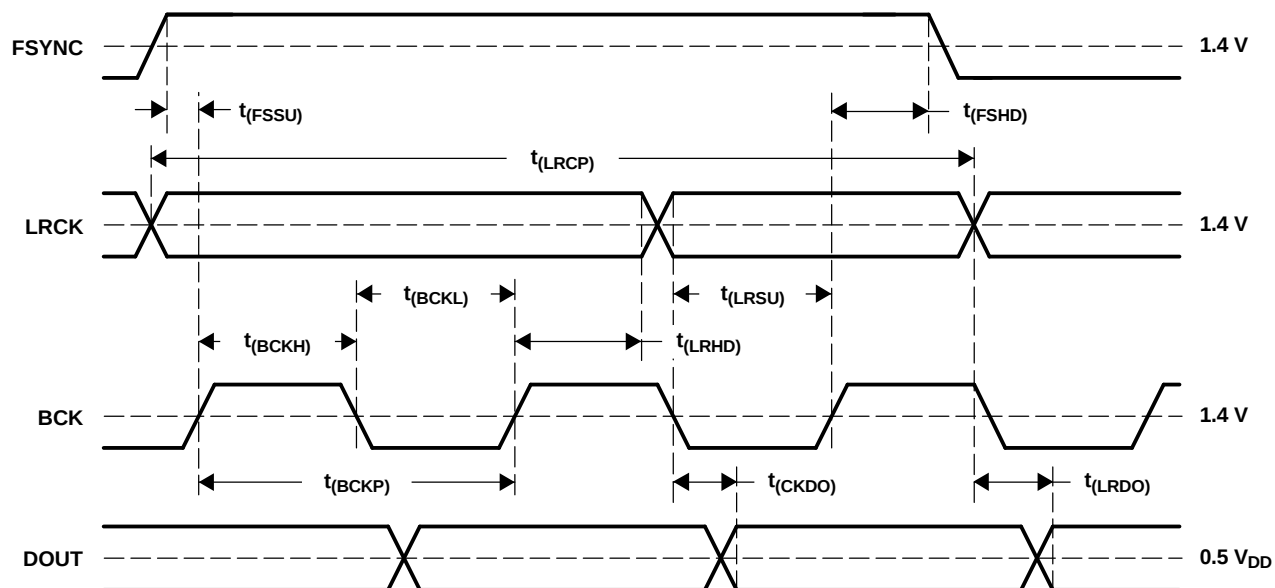
FORMAT 3: FMT[1:0] = 11

20-Bit, MSB-First, Right-Justified



T0016-12

Figure 24. Audio Data Format (Slave Mode: FSYNC, LRCK, and BCK Work as Inputs)



T0017-01

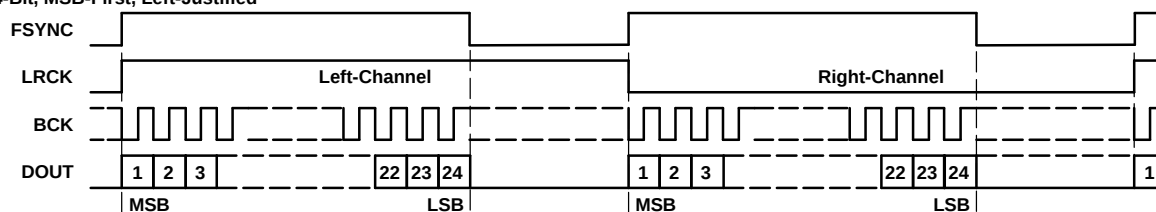
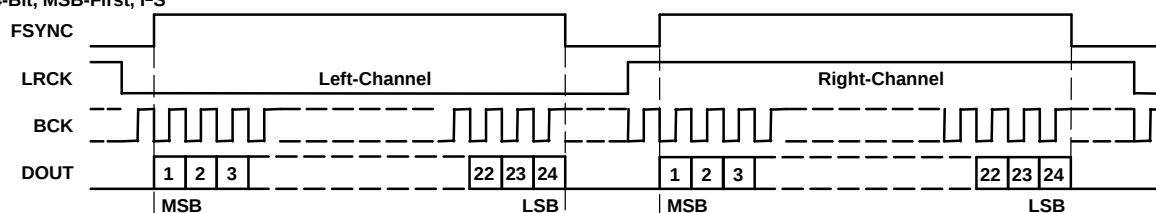
PARAMETER		MIN	TYP	MAX	UNIT
$t_{(BCKP)}$	BCK period	150			ns
$t_{(BCKH)}$	BCK pulse duration, high	60			ns
$t_{(BCKL)}$	BCK pulse duration, low	60			ns
$t_{(LRSU)}$	LRCK setup time to BCK rising edge	40			ns
$t_{(LRHD)}$	LRCK hold time to BCK rising edge	20			ns
$t_{(LRCP)}$	LRCK period	10			μs
$t_{(FSSU)}$	FSYNC setup time to BCK rising edge	20			ns
$t_{(FSHD)}$	FSYNC hold time to BCK rising edge	20			ns
$t_{(CKDO)}$	Delay time, BCK falling edge to DOUT valid	-10		20	ns
$t_{(LRDO)}$	Delay time, LRCK edge to DOUT valid	-10		20	ns
t_r	Rise time of all signals			10	ns
t_f	Fall time of all signals			10	ns

NOTE: Timing measurement reference level is $(V_{IH} + V_{IL})/2$. Rise and fall times are measured from 10% to 90% of IN/OUT signal swing. Load capacitance of DOUT is 20 pF.

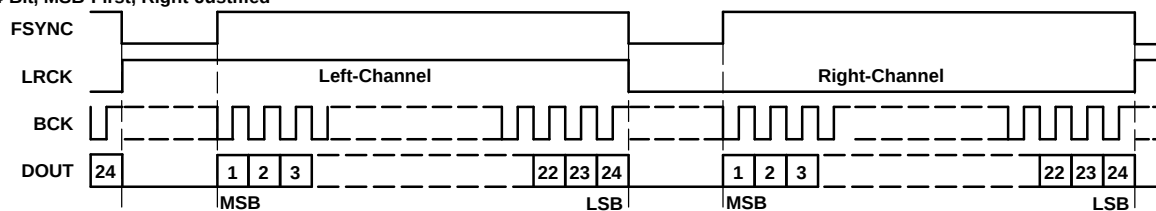
Figure 25. Audio Data Interface Timing (Slave Mode: FSYNC, LRCK, and BCK Work as Inputs)

FORMAT 0: FMT[1:0] = 00

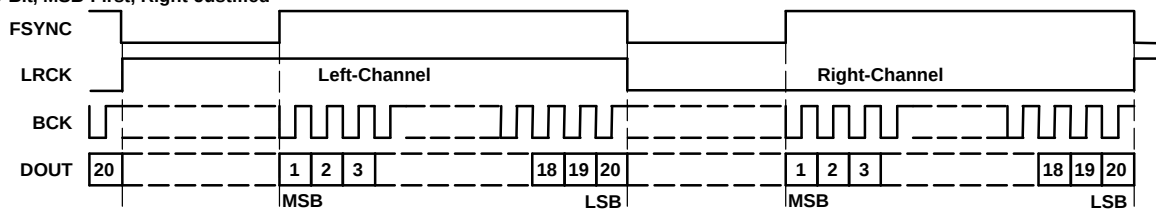
24-Bit, MSB-First, Left-Justified

**FORMAT 1: FMT[1:0] = 01**24-Bit, MSB-First, I²S**FORMAT 2: FMT[1:0] = 10**

24-Bit, MSB-First, Right-Justified

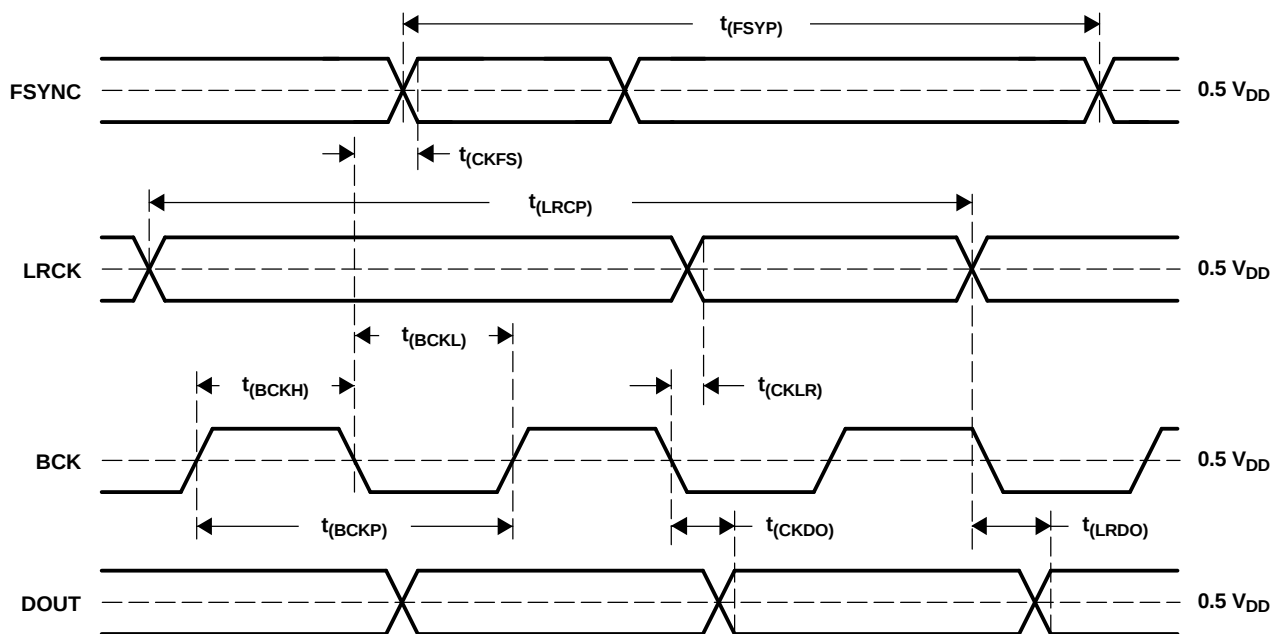
**FORMAT 3: FMT[1:0] = 11**

20-Bit, MSB-First, Right-Justified



T0016-13

Figure 26. Audio Data Format (Master Mode: FSYNC, LRCK, and BCK Work as Outputs)



T0018-01

PARAMETER		MIN	TYP	MAX	UNIT
$t_{(BCKP)}$	BCK period	150	$1/(64 f_s)$	1200	ns
$t_{(BCKH)}$	BCK pulse duration, high	75		600	ns
$t_{(BCKL)}$	BCK pulse duration, low	75		600	ns
$t_{(CKLR)}$	Delay time, BCK falling edge to LRCK valid	-10		20	ns
$t_{(LRCP)}$	LRCK period	10	$1/f_s$	80	μs
$t_{(CKFS)}$	Delay time, BCK falling edge to FSYNC valid	-10		20	ns
$t_{(FSYP)}$	FSYNC period	5	$1/(2 f_s)$	40	μs
$t_{(CKDO)}$	Delay time, BCK falling edge to DOUT valid	-10		20	ns
$t_{(LRDO)}$	Delay time, LRCK edge to DOUT valid	-10		20	ns
t_r	Rise time of all signals			10	ns
t_f	Fall time of all signals			10	ns

NOTE: Timing measurement reference level is $(V_{IH} + V_{IL}) / 2$. Rise and fall times are measured from 10% to 90% of IN/OUT signal swing. Load capacitance of all signals is 20 pF.

Figure 27. Audio Data Interface Timing (Master Mode: FSYNC, LRCK, and BCK Work as Outputs)

Synchronization With Digital Audio System

In slave mode, the PCM1802 operates under LRCK, synchronized with system clock SCKI. The PCM1802 does not need a specific phase relationship between LRCK and SCKI, but does require the synchronization of LRCK and SCKI.

If the relationship between LRCK and SCKI changes more than ± 6 BCKs for 64 BCK/frame (± 5 BCKs for 48 BCK/frame) during one sample period due to LRCK or SCKI jitter, internal operation of the ADC halts within $1/f_s$ and digital output is forced into BPZ code until resynchronization between LRCK and SCKI is completed.

In the case of changes less than ± 5 BCKs for 64 BCK/frame (± 4 BCKs for 48 BCK/frame), resynchronization does not occur.

Figure 28 illustrates the digital output response for loss of synchronization and resynchronization. During undefined data, some noise might be generated in the audio signal. Also, the transition of normal to undefined data and undefined or zero data to normal creates a data discontinuity in the digital output, which can generate some noise in the audio signal.

It is recommended to set $\overline{\text{PDWN}}$ low to get stable analog performance when the sampling rate, interface mode, data format, or oversampling control is changed.

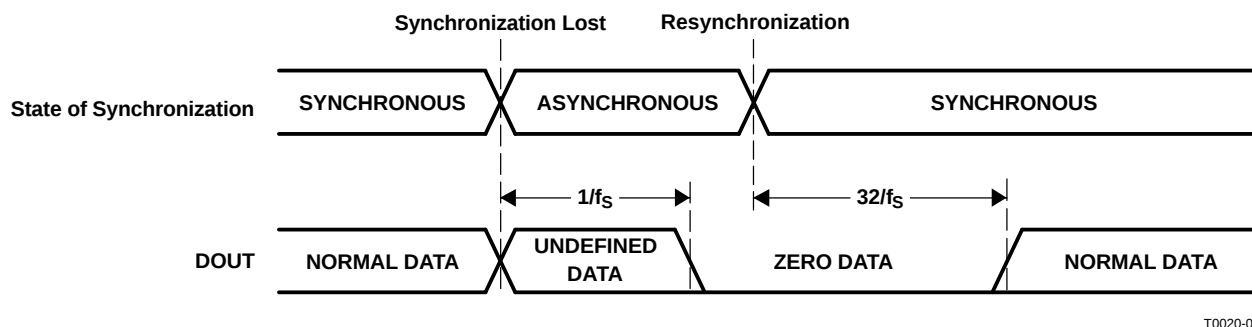


Figure 28. ADC Digital Output for Loss of Synchronization and Resynchronization

Power Down, HPF Bypass, Oversampling Control

$\overline{\text{PDWN}}$ (pin 7) controls the entire ADC operation. During power-down mode, both the supply current for the analog portion and the clock signal for the digital portion are shut down, and power dissipation is minimized. Also, DOUT (pin 12) is disabled and no system clock is accepted during power-down mode.

Power-Down Control

$\overline{\text{PDWN}}$	MODE
LOW	Power-down mode
HIGH	Normal operation mode

The built-in function for dc component rejection can be bypassed using the BYPAS (pin 8) control. In bypass mode, the dc components of the analog input signal, internal dc offset, etc., are also converted and included in the digital output data.

HPF Bypass Control

BYPAS	HPF (HIGH-PASS FILTER) MODE
LOW	Normal (no dc component on DOUT) mode
HIGH	Bypass (dc component on DOUT) mode

OSR (pin 16) controls the oversampling ratio of the delta-sigma modulator, $\times 64$ or $\times 128$. The $\times 128$ mode is available for $f_s < 50$ kHz, and must be used carefully as performance is affected by the duty cycle of the $384 f_s$ system clock.

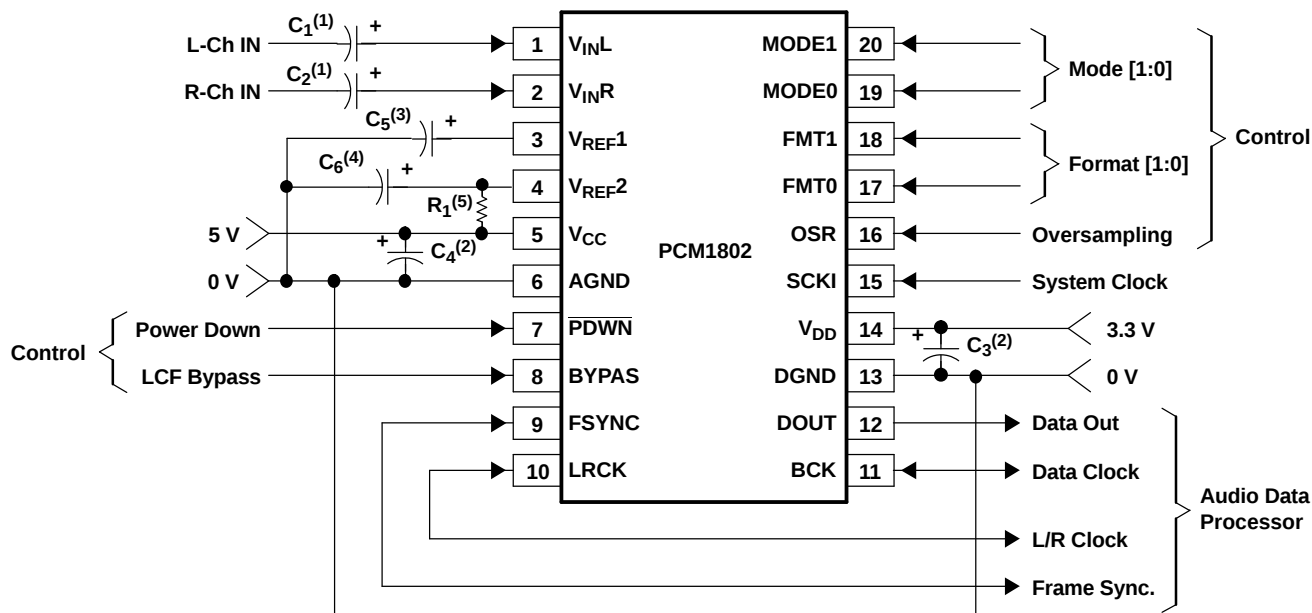
Oversampling Control

OSR	OVERSAMPLING RATIO
LOW	$\times 64$
HIGH	$\times 128$ ($f_s < 50$ kHz)

APPLICATION INFORMATION

Typical Circuit Connection Diagram

Figure 29 illustrates a typical circuit connection diagram in which the cutoff frequency of the input HPF is about 8 Hz.



S0026-02

- (1) C_1, C_2 : A 1- μ F capacitor gives 8-Hz ($\tau = 1 \mu\text{F} \times 20 \text{ k}\Omega$) cutoff frequency for input HPF in normal operation and requires a power-on settling time with a 20-ms time constant during the power-on initialization period.
- (2) C_3, C_4 : Bypass capacitors, 0.1- μ F ceramic and 10- μ F tantalum, depending on layout and power supply
- (3) C_5 : 0.1- μ F ceramic and 10- μ F tantalum capacitors are recommended.
- (4) C_6 : 0.1- μ F ceramic and 10- μ F tantalum capacitors are recommended when using a noisy analog power supply. These capacitor are not required for a clean analog supply.
- (5) R_1 : A 1-k Ω resistor is recommended when using a noisy analog power supply. This resistor is shorted for a clean analog supply.

Figure 29. Typical Circuit Connection

APPLICATION INFORMATION (continued)

Board Design and Layout Considerations

V_{CC} , V_{DD} Pins

The digital and analog power supply lines to the PCM1802 should be bypassed to the corresponding ground pins with 0.1- μ F ceramic and 10- μ F tantalum capacitors as close to the pins as possible to maximize the dynamic performance of the ADC.

AGND, DGND Pins

To maximize the dynamic performance of the PCM1802, the analog and digital grounds are not connected internally. These grounds should have low impedance to avoid digital noise feeding back into the analog ground. They should be connected directly to each other under the parts to reduce the potential noise problem.

V_{IN} Pins

A 1- μ F capacitor is recommended as an ac-coupling capacitor, which gives an 8-Hz cutoff frequency. If a higher full-scale input voltage is required, it can be accommodated by adding only one series resistor to each V_{IN} pin.

V_{REF1} Pin

A ceramic capacitor of 0.1 μ F and an electrolytic capacitor of 10 μ F are recommended between V_{REF1} and AGND to ensure low source impedance for the ADC references. These capacitors should be located as close as possible to the V_{REF1} pin to reduce dynamic errors on the ADC references.

V_{REF2} Pin

The differential voltage between V_{REF2} and AGND sets the analog input full-scale range. A ceramic capacitor of 0.1 μ F and an electrolytic capacitor of 10 μ F are recommended between V_{REF2} and AGND with the insertion of a 1-k Ω resistor between V_{CC} and V_{REF2} when using a noisy analog power supply. These capacitors and resistor are not required for a clean analog supply. These capacitors should be located as close as possible to the V_{REF2} pin to reduce dynamic errors on the ADC references. Full-scale input level is affected by this 1-k Ω resistor, decreasing by 3%.

DOUT Pin

The DOUT pin has enough load drive capability, but locating a buffer near the PCM1802 and minimizing load capacitance is recommended if the DOUT line is long, in order to minimize the digital-analog crosstalk and maximize the dynamic performance of the ADC.

System Clock

The quality of the system clock can influence dynamic performance, as the PCM1802 operates based on the system clock. In slave mode, it may be necessary to consider the system-clock duty cycle, jitter, and the time difference between the system clock transition and the BCK or LRCK transition.

PACKAGING INFORMATION

Orderable Device	Status ⁽¹⁾	Package Type	Package Drawing	Pins	Package Qty	Eco Plan ⁽²⁾	Lead/ Ball Finish	MSL Peak Temp ⁽³⁾	Samples (Requires Login)
PCM1802DB	ACTIVE	SSOP	DB	20	65	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM	Request Free Samples
PCM1802DBG4	ACTIVE	SSOP	DB	20	65	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM	Request Free Samples
PCM1802DBR	ACTIVE	SSOP	DB	20	2000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM	Purchase Samples
PCM1802DBRG4	ACTIVE	SSOP	DB	20	2000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM	Purchase Samples
PCM1802S1DB	OBSOLETE	SSOP	DB	20		TBD	Call TI	Call TI	Samples Not Available
PCM1802S1DBG4	OBSOLETE	SSOP	DB	20		TBD	Call TI	Call TI	Samples Not Available

⁽¹⁾ The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

⁽²⁾ Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check <http://www.ti.com/productcontent> for the latest availability information and additional product content details.

TBD: The Pb-Free/Green conversion plan has not been defined.

Pb-Free (RoHS): TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.

Pb-Free (RoHS Exempt): This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

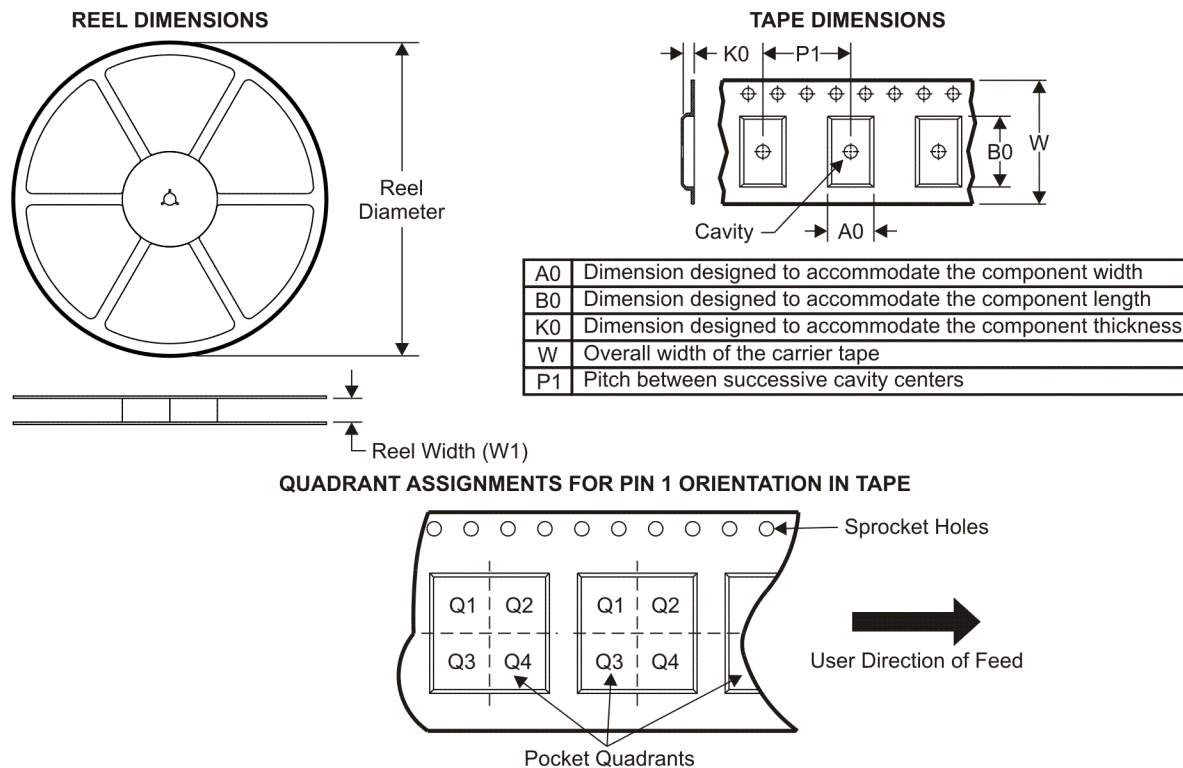
Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

⁽³⁾ MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

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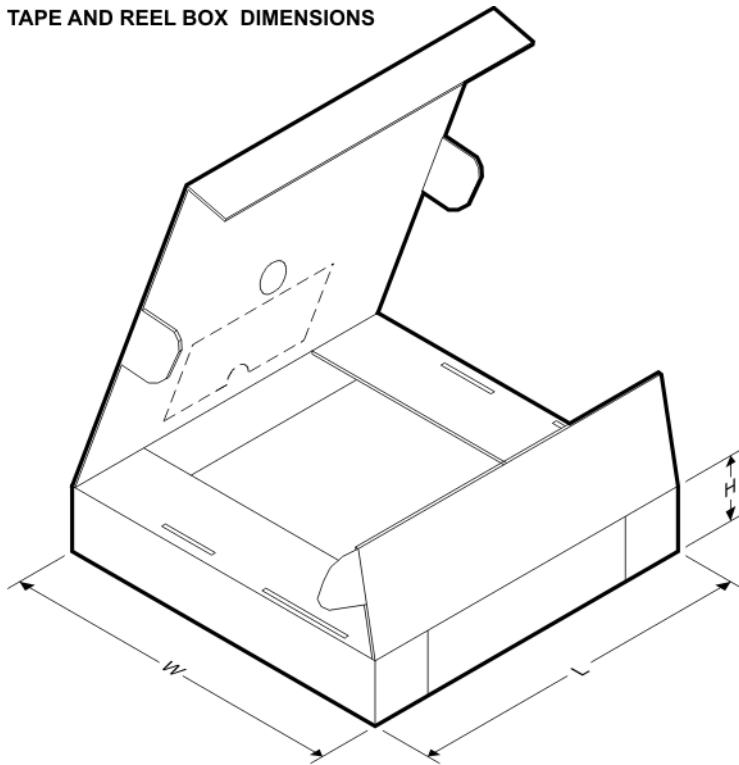
TAPE AND REEL INFORMATION



*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
PCM1802DBR	SSOP	DB	20	2000	330.0	17.4	8.5	7.6	2.4	12.0	16.0	Q1

TAPE AND REEL BOX DIMENSIONS



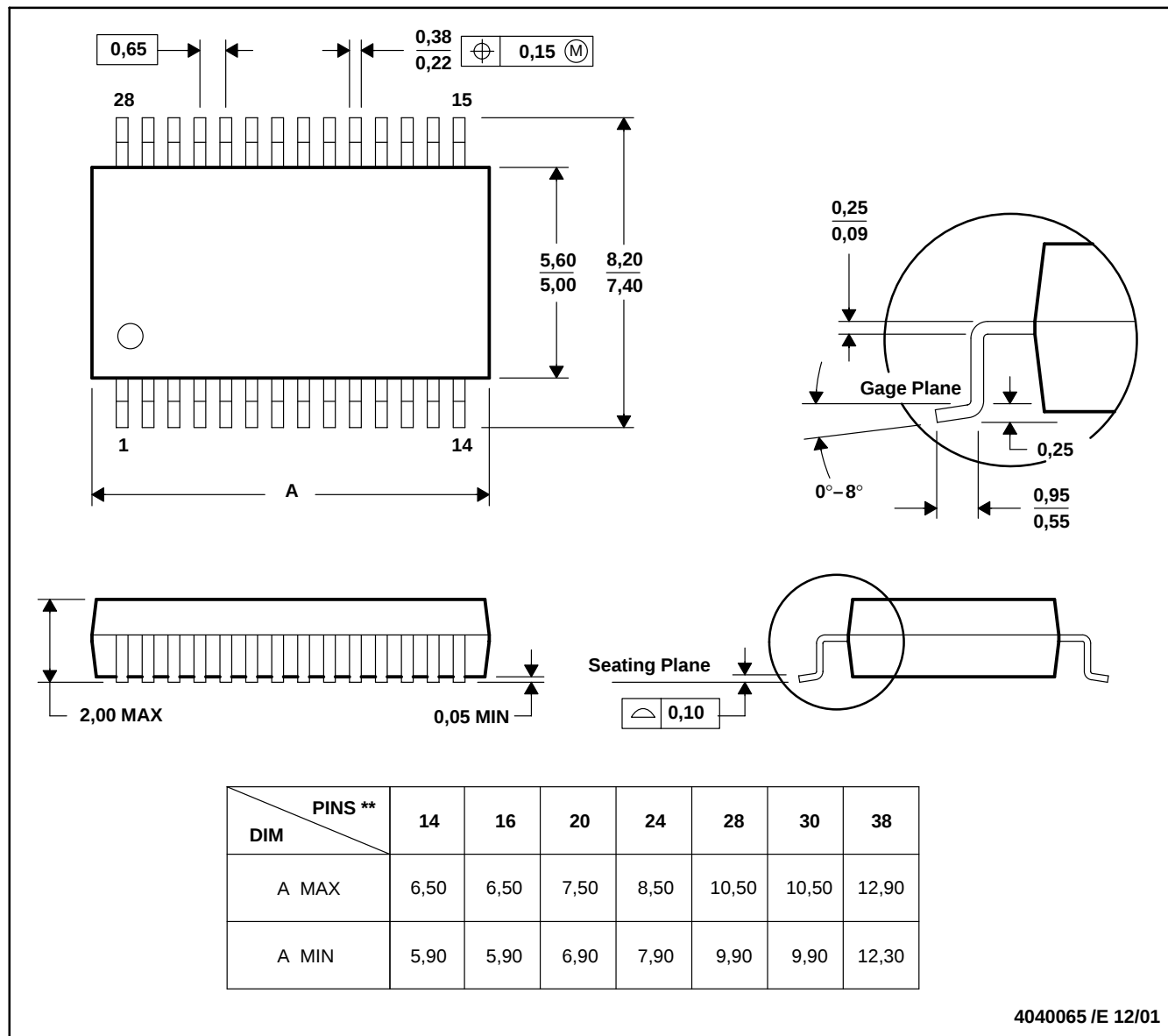
*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
PCM1802DBR	SSOP	DB	20	2000	336.6	336.6	28.6

DB (R-PDSO-G**)

PLASTIC SMALL-OUTLINE

28 PINS SHOWN



- NOTES: A. All linear dimensions are in millimeters.
 B. This drawing is subject to change without notice.
 C. Body dimensions do not include mold flash or protrusion not to exceed 0,15.
 D. Falls within JEDEC MO-150

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